

PC10372, Mathematics 2

Workshop Sheet 5 Solutions

1) $\frac{\partial^2 f}{\partial x^2} = 0$, $\frac{\partial^2 f}{\partial y^2} = 2xz^3$ and $\frac{\partial^2 f}{\partial z^2} = 6xy^2z$ so

$$\nabla^2 f = 2xz^3 + 6xy^2z$$

2) $\frac{\partial^2 \mathbf{v}}{\partial x^2} = 3x\mathbf{k}$, $\frac{\partial^2 \mathbf{v}}{\partial y^2} = 0$ and $\frac{\partial^2 \mathbf{v}}{\partial z^2} = 0$ so

$$\nabla^2 \mathbf{v} = 3x\mathbf{k}$$

3)

$$\mathbf{r} \times \mathbf{s} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x & y & z \\ z & x & y \end{vmatrix} = \mathbf{i}(y^2 - xz) + \mathbf{j}(z^2 - xy) + \mathbf{k}(x^2 - yz)$$

$$\nabla \times \mathbf{r} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix} = 0$$

$$\nabla \times \mathbf{s} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ z & x & y \end{vmatrix} = \mathbf{i} + \mathbf{j} + \mathbf{k}$$

$$\nabla \cdot \mathbf{r} = 1 + 1 + 1 = 3$$

$$\nabla \cdot \mathbf{s} = 0 + 0 + 0 = 0$$

$$\nabla \cdot (\mathbf{r} \times \mathbf{s}) = -z - x - y$$

$$(\nabla \times \mathbf{r}) \cdot \mathbf{s} = 0$$

$$(\nabla \times \mathbf{s}) \cdot \mathbf{r} = (\mathbf{i} + \mathbf{j} + \mathbf{k}) \cdot (x\mathbf{i} + y\mathbf{j} + z\mathbf{k}) = x + y + z$$

Substituting demonstrates that $\nabla \cdot (\mathbf{r} \times \mathbf{s}) = (\nabla \times \mathbf{r}) \cdot \mathbf{s} - (\nabla \times \mathbf{s}) \cdot \mathbf{r}$.

$$\begin{aligned} \nabla \times (\mathbf{r} \times \mathbf{s}) &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^2 - zx & z^2 - xy & x^2 - yz \end{vmatrix} \\ &= \mathbf{i}(-3z) = \mathbf{j}(-3x) + \mathbf{k}(-3y) = -3\mathbf{s} \end{aligned}$$

$$\begin{aligned}
\underline{\mathbf{r}}(\nabla \cdot \underline{\mathbf{s}}) - \underline{\mathbf{s}}(\nabla \cdot \underline{\mathbf{r}}) + (\underline{\mathbf{s}} \cdot \nabla) \underline{\mathbf{r}} - (\underline{\mathbf{r}} \cdot \nabla) \underline{\mathbf{s}} &= 0 - 3\underline{\mathbf{s}} \\
&+ \left(z \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} + y \frac{\partial}{\partial z} \right) (x\underline{\mathbf{i}} + y\underline{\mathbf{j}} + z\underline{\mathbf{k}}) \\
&- \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} \right) (z\underline{\mathbf{i}} + x\underline{\mathbf{j}} + y\underline{\mathbf{k}}) \\
&= -3\underline{\mathbf{s}} + (z\underline{\mathbf{i}} + x\underline{\mathbf{j}} + y\underline{\mathbf{k}}) - (x\underline{\mathbf{j}} + y\underline{\mathbf{k}} + z\underline{\mathbf{i}}) \\
&= -3\underline{\mathbf{s}}
\end{aligned}$$

showing that $\nabla \times (\underline{\mathbf{r}} \times \underline{\mathbf{s}}) = \underline{\mathbf{r}}(\nabla \cdot \underline{\mathbf{s}}) - \underline{\mathbf{s}}(\nabla \cdot \underline{\mathbf{r}}) + (\underline{\mathbf{s}} \cdot \nabla) \underline{\mathbf{r}} - (\underline{\mathbf{r}} \cdot \nabla) \underline{\mathbf{s}}$

4) Cartesian: $f = x, \nabla f = \underline{\mathbf{i}}$

Cylindrical polar: $f = r \cos \theta, \nabla f = \cos \theta \hat{\underline{\mathbf{r}}} - \sin \theta \hat{\underline{\boldsymbol{\theta}}}$

Spherical polar: $f = r \sin \theta \cos \phi, \nabla f = \sin \theta \cos \phi \hat{\underline{\mathbf{r}}} + \cos \theta \cos \phi \hat{\underline{\boldsymbol{\theta}}} - \sin \phi \hat{\underline{\boldsymbol{\phi}}}$

Since the results must be independent of the coordinate system, these results must all be the same so equating the Cartesian and spherical polar results gives

$$\underline{\mathbf{i}} = \sin \theta \cos \theta \hat{\underline{\mathbf{r}}} + \cos \theta \cos \phi \hat{\underline{\boldsymbol{\theta}}} - \sin \phi \hat{\underline{\boldsymbol{\phi}}}$$

as required.