














```

00001 ;=====
00002 ; EMULATOR should be defined when controlled by the laptop ;
00003 ; undefined running as a mezzanine to the digital board ;
00004 ; TEST should be defined when using the test board for initial debugging ;
00005 ; undefined when using the real board ;
00006 ; ;
00007 #DEFINE EMULATOR
00008 ; #DEFINE TEST
00009 ;
00010 ;=====
00011 ; Number of 256 word blocks to include in the CRC ;
00012 ; ;
00013 #DEFINE PROGBLOCKS 8
00014 ;
00015 ;=====
00016 ; This is the program version number Should be the same as IDLOCS ;
00017 ; ;
00018 #DEFINE I_VN_M 0X04
00019 #DEFINE I_VN_L 0X01
00020 ;
00021 ;=====
00022
00023 LIST P=16F877,N=0
00024 TITLE " ALMA Optical Receiver microcontroller
00025
00026 INCLUDE <D16F877.INC> ;
00001 ; P16F877.INC Standard Header File, Version 1.00 Microchip Technology Inc
00372 LIST
00027
00028 ;__CONFIG _CP_OFF & _DEBUG_OFF & _WRT_ENABLE_OFF & _LVP_ON & _BODEN_ON & _PWRTE_OFF & _WDT_ON & _XT_OSC
2007 3D32 00029 __CONFIG _CP_OFF & _DEBUG_OFF & _WRT_ENABLE_OFF & _LVP_OFF & _BODEN_OFF & _PWRTE_ON & _WDT_OFF & _HS_OSC
2000 0000 0004 0000 00030 __IDLOCS 0X0401
0001
00031
00032 INCLUDE <DCBMACRO.INC>
00001 ; DCBMACRO.INC Simple macros. Version 1.10 dcb
00337 LIST
00033 ;
00034 ; NOTE ON PAGES AND BANKS
00035 ;~~~~~
00036 ; All code resides on page zero so paging is not an issue;
00037 ; All used RAM is in bank zero so bank switching is only an issue for accessing
00038 ; Special Function Registers. All modules and subroutines which access outside
00039 ; bank zero must return to bank zero on completion.
00040 ; Interrupt can occur when any bank is selected. However the context registers
00041 ; (W,FSR & Status) are mapped across all banks and are saved to RAM above $70
00042 ; which is also mapped across all banks
00043
00044

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00045 ; This is the number of bytes in a block read.  It must be 8 in the final system
00046 #ifdef EMULATOR
00047     #DEFINE BLOCKLEN    32
00048 ELSE
00049     #DEFINE BLOCKLEN    8
00050 #endif
00051
00052 ; These are the memory locations which are read by the M&C bus
00053 ; They are all in bank zero and are arranged in groups of eight
00054
00055     #DEFINE MONITOR_POINTS_BASE 0X20
00056     #DEFINE _STATUS1           0X20    ; Primary status
00057     #DEFINE _STATUS2           0X21    ; Secondary status
00058
00059     #DEFINE EXTERNAL_VALUES_BASE 0X22
00060     #DEFINE _OP0VAL_M           0X22    ; Current value - Optical Rx 0
00061     #DEFINE _OP0VAL_L           0X23
00062     #DEFINE _OP1VAL_M           0X24    ; Current value - Optical Rx 1
00063     #DEFINE _OP1VAL_L           0X25
00064     #DEFINE _OP2VAL_M           0X26    ; Current value - Optical Rx 2
00065     #DEFINE _OP2VAL_L           0X27
00066
00067     #DEFINE INTERNAL_VALUES_BASE 0X28
00068     #DEFINE _VNVAL_M            0X28    ; Current value - Negative PSU
00069     #DEFINE _VNVAL_L            0X29
00070     #DEFINE _VPVAL_M            0X2A    ; Current value - Positive PSU
00071     #DEFINE _VPVAL_L            0X2B
00072     #DEFINE _VCVAL_M            0X2C    ; Current value - Control PSU
00073     #DEFINE _VCVAL_L            0X2D
00074     #DEFINE _TMPVAL_M           0X2E    ; Current value - Temperature
00075     #DEFINE _TMPVAL_L           0X2F    ;
00076
00077     #DEFINE EXTERNAL_FAULTS_BASE 0X32
00078     #DEFINE _OP0FLT_M           0X32    ; Fault value - Optical Rx 0
00079     #DEFINE _OP0FLT_L           0X33    ;
00080     #DEFINE _OP1FLT_M           0X34    ; Fault value - Optical Rx 1
00081     #DEFINE _OP1FLT_L           0X35    ;
00082     #DEFINE _OP2FLT_M           0X36    ; Fault value - Optical Rx 2
00083     #DEFINE _OP2FLT_L           0X37    ;
00084
00085     #DEFINE INTERNAL_FAULT_BASE 0X38
00086     #DEFINE _VNFLT_M            0X38    ; Fault value - Negative PSU
00087     #DEFINE _VNFLT_L            0X39
00088     #DEFINE _VPFLT_M            0X3A    ; Fault value - Positive PSU
00089     #DEFINE _VPFLT_L            0X3B
00090     #DEFINE _VCFLT_M            0X3C    ; Fault value - Control PSU
00091     #DEFINE _VCFLT_L            0X3D
00092     #DEFINE _TMPFLT_M           0X3E    ; Fault value - Temperature
00093     #DEFINE _TMPFLT_L           0X3F    ;
00094
00095     #DEFINE _COMMAND            0X40
00096
00097     #DEFINE EEPROM_START        0X42

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00098 #DEFINE EXTERNAL_LIMITS_BASE 0X42
00099 #DEFINE _OP1ULIM_M 0X42 ; Upper limit - Optical Rx 1
00100 #DEFINE _OP0LLIM 0X43 ; Lower Limit - Optical Rx 0
00101 #DEFINE _OP0ULIM_M 0X44 ; Upper limit - Optical Rx 0
00102 #DEFINE _OP1LLIM 0X45 ; Lower Limit - Optical Rx 1
00103 #DEFINE _OP2ULIM_M 0X46 ; Upper limit - Optical Rx 2
00104 #DEFINE _OP2LLIM 0X47 ; Lower Limit - Optical Rx 2
00105
00106 #DEFINE INTERNAL_LIMITS_BASE 0X48
00107 #DEFINE _VNULIM 0X48 ; Upper limit - Negative PSU
00108 #DEFINE _VNLLIM 0X49 ; Lower limit - Negative PSU
00109 #DEFINE _VPULIM 0X4A ; Upper limit - Positive PSU
00110 #DEFINE _VPLLIM 0X4B ; Lower limit - Positive PSU
00111 #DEFINE _VCULIM 0X4C ; Upper limit - Control PSU
00112 #DEFINE _VCLLIM 0X4D ; Lower limit - Control PSU
00113 #DEFINE _TMPULIM 0X4E ; Upper limit - Temperature
00114 #DEFINE _TMPLLIM 0X4F ; Lower limit - Temperature
00115
00116 #DEFINE FINE_TUNE_BASE 0X50
00117 #DEFINE _OP0FT_M 0X50 ; Fine Tune - Optical Rx 0
00118 #DEFINE _OP0FT_L 0X51
00119 #DEFINE _OP1FT_M 0X52 ; Fine Tune - Optical Rx 1
00120 #DEFINE _OP1FT_L 0X53
00121 #DEFINE _OP2FT_M 0X54 ; Fine Tune - Optical Rx 2
00122 #DEFINE _OP2FT_L 0X55
00123
00124 #DEFINE CALIBRATION_BASE 0X56
00125 #DEFINE _OP0CAL1_M 0X56 ; 0dB cal - Optical Rx 0
00126 #DEFINE _OP0CAL1_L 0X57
00127 #DEFINE _OP0CAL0 0X58 ; Zero cal - Optical Rx 0
00128 #DEFINE _OP1CAL1_M 0X59 ; 0dB cal - Optical Rx 1
00129 #DEFINE _OP1CAL1_L 0X5A
00130 #DEFINE _OP1CAL0 0X5B ; Zero cal - Optical Rx 1
00131 #DEFINE _OP2CAL1_M 0X5C ; 0dB cal - Optical Rx 2
00132 #DEFINE _OP2CAL1_L 0X5D
00133 #DEFINE _OP2CAL0 0X5E ; Zero cal - Optical Rx 2
00134
00135 #DEFINE _ID0 0X60 ; Identity Bytes
00136 #DEFINE _ID1 0X61
00137 #DEFINE _ID2 0X62
00138 #DEFINE _CHECKSUM 0X63
00139
00140
00141 #DEFINE _SN_M 0X64 ; Board Serial Number
00142 #DEFINE _SN_L 0X65
00143 #DEFINE _VN_M 0X66 ; Program version number
00144 #DEFINE _VN_L 0X67
00145
00146 #DEFINE _CRC_M 0X68 ; CRC of program
00147 #DEFINE _CRC_L 0X69
00148
00149
00150 ;=====

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```

00151 ; These are registers and bits used by the program - mapped across all banks
00152
00153     #DEFINE RESERVED    0X70      ; for ICD
00154
00155     #DEFINE SCNT         0X71      ; Usually a counter in subroutines
00156     #DEFINE LCNT        0X72      ; Usually a counter in program
00157     #DEFINE SHFT_M      0X73
00158     #DEFINE SHFT_L      0X74
00159
00160     #DEFINE TEMPO       0X75
00161     #DEFINE TEMP1      0X76
00162
00163     #DEFINE CAL0        0X77      ; Used in calibration routine
00164     #DEFINE CAL1        0X78      ;
00165     #DEFINE CAL2        0X79      ;
00166     #DEFINE CCNT        0X7A      ;
00167
00168     #DEFINE TCNT        0X7B      ; Time out counter
00169
00170     #DEFINE ICNT        0X7C      ; Counter in the interrupt routine
00171     #DEFINE WSAVE       0X7D      ; Save W in interrupt
00172     #DEFINE SSAVE       0X7E      ; Save Status in interrupt
00173     #DEFINE FSAVE       0X7F      ; Save FSR in interrupt
00174
00175 ;=====
00176 ; These are names for the bits in the ports
00177 ;
00178     #DEFINE ANALOG0     PORTA,0 ;Analog inputs (multiplexed)      a
00179     #DEFINE ANALOG1     PORTA,1 ;|                                a
00180     #DEFINE ASEL0       PORTE,0 ;Analog multiplexer selects      o
00181     #DEFINE ASEL1       PORTE,1 ;|                                o
00182
00183     #DEFINE ZCSIN       PORTB,0 ;Copy of A5 for interrupt
00184     #DEFINE ZCSN        PORTA,5 ;Hardware SPI bus (to AMBSI)      i
00185     #DEFINE ZCLK        PORTC,3 ;|                                o
00186     #DEFINE ZDI         PORTC,4 ;|                                i
00187     #DEFINE ZDO         PORTC,5 ;|                                o
00188
00189     #DEFINE DCLK        PORTC,0 ;Software SPI bus (ADC and DAC)  o
00190     #DEFINE DDI         PORTC,1 ;|                                i
00191     #DEFINE DDO         PORTC,2 ;|                                o
00192     #DEFINE ACSN        PORTC,6 ;|                                o
00193     #DEFINE DCSN        PORTC,7 ;|                                o
00194
00195     #DEFINE VPENN       PORTB,1 ;Positive PSU enable      o
00196     #DEFINE VNENN       PORTB,2 ;Negative PSU enable      o
00197     #DEFINE EDFASD      PORTB,4 ;EDFA shut down line     o
00198
00199     #DEFINE SNREQN      PORTB,5 ;Request serial number    o
00200     #DEFINE SNIN        PORTE,2 ;Read serial number      i
00201
00202     #DEFINE LEDSN       PORTD      ; LEDs                      o
00203     #DEFINE EDFALEDN    PORTD,0 ;

```

```

00204     #DEFINE PSULEDN     PORTD,1 ;
00205
00206 ;=====
00207 ; These are constants for the standard PSU shutdown modes.  Values 0-3 are
00208 ; also the analog multiplexer control codes
00209
00210     #DEFINE PSU_VN     0 ; Vneg fault
00211     #DEFINE PSU_VP     1 ; Vpos fault
00212     #DEFINE PSU_VC     2 ; Vcon fault
00213     #DEFINE PSU_TMP    3 ; Temp fault
00214     #DEFINE PSU_MC     4 ; M&C command
00215
00216 ; These are constants for the EDFA shutdown modes
00217     #DEFINE EDF_R0     0 ; Receiver 0 fault
00218     #DEFINE EDF_R1     1 ; Receiver 1 fault
00219
00220     #DEFINE EDF_R2     2 ; Receiver 2 fault
00221     #DEFINE EDF_VC     3 ; Control supply fault
00222     #DEFINE EDF_MC     4 ; M&C command
00223     #DEFINE EDF_TO     5 ; Time out
00224
00225 ; These are constants for the secondary status codes for PSU no start
00226
00227     #DEFINE ST2P_VCX   0X42 ; Control voltage at startup
00228     #DEFINE ST2P_TMPX  0X01 ; Temperature at startup
00229
00230 ; These are individual bits in the primary status word
00231
00232     #DEFINE ST1_EDFA   _STATUS1,7 ; Optical shutdown commanded
00233     #DEFINE ST1_PSU    _STATUS1,6 ; The main PSUs are off
00234     #DEFINE ST1_NOSN   _STATUS1,5 ; Set if serial number is invalid
00235     #DEFINE ST1_EECSF  _STATUS1,4 ; t when EEPROM reads bad checksum
00236
00237
00238 ;=====
00239 ; These are constants for the M&C command codes.
00240
00241     #DEFINE CMD_START  0X00
00242
00243 ; These are constants for the M&C protocol control codes.
00244
00245     #DEFINE MC_IDR     0XB0
00246     #DEFINE MC_CMD     0XA8
00247     #DEFINE MC_MON     0XA0
00248     #DEFINE MC_ACK     0X59
00249
00250 ;=====
00251 ; These are initialization values for configuration registers and ports
00252
00253     #DEFINE I_TRISA    0XFF ; Port A is all inputs
00254     #DEFINE I_TRISB    0X01 ; Port B0 is int input
00255     #DEFINE I_TRISC    0X1A ; PortC bits 1,3,4 are inputs
00256     #DEFINE I_TRISD    0X00 ; PortD all outputs

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```

00257 #DEFINE I_TRISE      0X04    ; PortE bit 2 is input
00258
00259
00260 #DEFINE I_PORTB      0XFF    ; PSUENn, EDFAn, SNREQn off
00261 #DEFINE I_PORTC      0XC0    ; CSn, DOUTs,CLKs off
00262 #DEFINE I_PORTD      0XFC    ; PSULEDn, EDFALEDn on. Others off
00263 #DEFINE I_PORTE      0XF0    ; Analog Multiplexer at zero
00264
00265 #DEFINE I_ADCON0      0X80    ; ADC - Fo/32; chan 0; all off
00266 #DEFINE I_ADCON1      0X85    ; ADC - right justified; mode 5
00267
00268 #DEFINE I_SSPSTAT     0X00    ; Falling edge clock. BF cleared
00269 #DEFINE I_SSPCON      0X04    ; Fault bits cleared. SPI disabled
00270                               ; Clock idle low. SPI mode 4
00271
00272 #DEFINE I_INTCON      0X10    ; External interrupts enabled
00273
00274 #DEFINE I_OPTION      0X0F    ; Pull ups enabled ; RB0 falling edge
00275                               ; Post scale WDT by 128 (896-4224 mS)
00276 #DEFINE I_T1CON       0X31    ; Prescaler=8 ; External oscillator off
00277                               ; Internal clock ; enabled

```

```

00278 ;=====
0000 00279     ORG 0
0000 2900 00280     GOTO    START
0004 00281
00282     ORG 0X004
00283     INCLUDE INTS.INC

00001     PAGE
00002     SUBTITLE " Interrupt handler "
00003
00004 ; This section handles the interrupt which can only be caused by the
00005 ; rising edge of the chip select line at the start of an SPI transfer
00006 ;
00007 ;#####;
00008 ; ;
00009 ; This macro is to send and receive a byte on the SPI ;
00010 ; W contains the byte to send and is replaced by the received byte ;
00011 ; _____;
00012
00013 SPIT    MACRO
00014         LOCAL    SPIT0
00015
00016         MOVWF    SSPBUF
00017         BANK1
00018 SPIT0   BTFSS    SSPSTAT,BF
00019         GOTO    SPIT0
00020         BANK0
00021         MOVFW    SSPBUF
00022
00023         ENDM;
00024
00025 ;#####;
00026 ; ;
00027 ; First section saves the W,STATUS and FSR registers and clears the flag ;
00028 ; and flashes the top LED ;
00029 ; _____;
00030
00031
0004 00FD 00032         MOVWF    WSAVE                ; Save the context
0005 0E03 00033         SWAPF    STATUS,W
0006 00FE 00034         MOVWF    SSAVE
0007 0804 00035         MOVF     FSR,W
0008 00FF 00036         MOVWF    FSAVE
00037
00038         BANK00
0009 1283     M     BCF STATUS,RP0
000A 1303     M     BCF STATUS,RP1
000B 3080 00039         MOVLW   0X80
000C 0688 00040         XORWF   PORTD,F
00041
00042 ;=====;
00043 ; ;
00044 ; Wait for a byte to be received.  Save the bottom three bits which might be ;

```



```

00045 ; the count. Then branch on the top five bits to the appropriate transfer ;
00046 ; type. If unrecognized then do nothing ;
00047 ; _____ ;
00048
00049          BANK1
000D  1683      M      BSF STATUS,RP0
000E  1C14      00050 M7_L0 BTFSS  SSPSTAT,BF          ; Wait for byte to be received
000F  280E      00051      GOTO   M7_L0
00052
00053          BANK0
0010  1283      M      BCF STATUS,RP0
00054      00054      ANDLF  0X07,SSPBUF,W          ; Extract the bottom three bit
0011  3007      M      MOVLW 0X07
0012  0513      M      ANDWF  SSPBUF,W
0013  00FC      00055      MOVWF  ICNT          ; and save in ICNT
00056      00056      ANDLF  0XF8,SSPBUF,F          ; and the top five bits
0014  30F8      M      MOVLW 0XF8
0015  0593      M      ANDWF  SSPBUF,F
00057
00058          SKPNEL SSPBUF,MC_IDR
0016  30B0      M      MOVLW 0XB0 ; w := k
0017  0213      M      SUBWF  SSPBUF,W ; w := reg1-k
0018  1903      M      SKPNZ ;
0019  2823      00059      GOTO   M7_ID
00060
00061          SKPNEL SSPBUF,MC_CMD          ; Or command (write to PIC)
001A  30A8      M      MOVLW 0XA8 ; w := k
001B  0213      M      SUBWF  SSPBUF,W ; w := reg1-k
001C  1903      M      SKPNZ ;
001D  2832      00062      GOTO   M7_CD
00063
00064          SKPNEL SSPBUF,MC_MON          ; Or monitor (read from PIC)
001E  30A0      M      MOVLW 0XA0 ; w := k
001F  0213      M      SUBWF  SSPBUF,W ; w := reg1-k
0020  1903      M      SKPNZ ;
0021  284B      00065      GOTO   M7_MN
00066
0022  285F      00067      GOTO   M7_NXT          ; If none of these goto end
00068
00069
00070 ; ===== ;
00071 ; ;
00072 ; An ID transfer. Return the three ID bytes in response to the next ;
00073 ; three transfers. The received data can be ignored ;
00074 ; _____ ;
00075
00076 M7_ID  MOVLF  _ID0,FSR          ; FSR points at first ID byte
0023  3060      M      MOVLW 0X60
0024  0084      M      MOVWF  FSR
00077      MOVLF  3,ICNT          ; Three ID bytes to send
0025  3003      M      MOVLW 3
0026  00FC      M      MOVWF  0X7C
00078

```

```

0027  0800      00079 M7_ID1 MOVFW  INDF          ; ID byte to SSPBUF wait until gone
00080          SPIT          ; Not concerned with rx data
0000          M            LOCAL  SPIT0
M
0028  0093          M            MOVWF  SSPBUF
M            BANK1
0029  1683          M            BSF   STATUS,RP0
002A  1C14          M SPIT0  BTFSS  SSPSTAT,BF
002B  282A          M            GOTO   SPIT0
M            BANK0
002C  1283          M            BCF   STATUS,RP0
002D  0813          M            MOVFW  SSPBUF
M
00081
002E  0A84          00082          INCF   FSR
002F  0BFC          00083          DECFSZ ICNT
0030  2827          00084          GOTO   M7_ID1
00085
0031  285F          00086          GOTO   M7_NXT
00087 ;=====;
00088 ; ;
00089 ; A command transfer. The count-1 has been stored in ICNT and the start ;
00090 ; address offset from the base is the next byte received. ICNT bytes of data;
00091 ; are then received and written to incrementing addresses. If the address is;
00092 ; not in the range 0x40-0x5F the write is inhibited ;
00093 ;-----;
00094
0032  3059          00095 M7_CD  MOVLW  MC_ACK          ; Send an acknowledge and wait for
00096          SPIT          ; receipt of address in W
0000          M            LOCAL  SPIT0
M
0033  0093          M            MOVWF  SSPBUF
M            BANK1
0034  1683          M            BSF   STATUS,RP0
0035  1C14          M SPIT0  BTFSS  SSPSTAT,BF
0036  2835          M            GOTO   SPIT0
M            BANK0
0037  1283          M            BCF   STATUS,RP0
0038  0813          M            MOVFW  SSPBUF
M
00097
00098 ;          ANDLW  0x7F          ; only seven bit addresses
00099 ;          ADDLF  MONITOR_POINTS_BASE,FSR,F          ; referring to base
00100 ;          NOP
00101 ;          NOP
0039  0084          00102          MOVWF  FSR          ; FSR points at the address
003A  0AFC          00103          INCF  ICNT,F
00104
003B  3000          00105 M7_CD1 MOVLW  0          ; Null data to SSPBUF wait until gone
00106          SPIT          ; W now contains received byte
0000          M            LOCAL  SPIT0
M
003C  0093          M            MOVWF  SSPBUF

```

```

M      BANK1
003D  1683      M      BSF  STATUS,RP0
003E  1C14      M SPIT0  BTFSS  SSPSTAT,BF
003F  283E      M      GOTO  SPIT0
M      BANK0
0040  1283      M      BCF  STATUS,RP0
0041  0813      M      MOVFW  SSPBUF
M
00107
0042  1F04      00108      BTFSS  FSR,6           ; Only permitted to write to address
0043  2847      00109      GOTO   M7_CD2         ; 0x4- and 0x5-. That is bit 6 set
0044  1A84      00110      BTFSC  FSR,5           ; and bit 5 clear
0045  2847      00111      GOTO   M7_CD2
00112
0046  0080      00113      MOVWF  INDF           ; Save byte in addressed location
00114
0047  0A84      00115 M7_CD2  INCF   FSR           ; Transfer size was defined
0048  0BFC      00116      DECFSZ ICNT          ; in low three bits of control byte
0049  283B      00117      GOTO   M7_CD1
00118
004A  285F      00119      GOTO   M7_NXT
00120
00121 ;=====;
00122 ;
00123 ; A monitor transfer. The count is fixed at forty bytes and the start
00124 ; address offset from the base is the next byte received. 40 bytes of data
00125 ; are then received and written to incrementing addresses.
00126 ;-----;
00127
00128
004B  3059      00129 M7_MN  MOVWLW  MC_ACK         ; Send an acknowledge and wait for
00130      SPIT           ; receipt of address
0000      M      LOCAL  SPIT0
M
004C  0093      M      MOVWF  SSPBUF
M      BANK1
004D  1683      M      BSF  STATUS,RP0
004E  1C14      M SPIT0  BTFSS  SSPSTAT,BF
004F  284E      M      GOTO  SPIT0
M      BANK0
0050  1283      M      BCF  STATUS,RP0
0051  0813      M      MOVFW  SSPBUF
M
00131
0052  0084      00132      MOVWF  FSR
00133      MOVLF  BLOCKLEN,ICNT           ; TESTMODE all monitor transfers are 36 bytes
M      MOVLW  32
0053  3020      M      MOVWF  0X7C
0054  00FC      M
00134
0055  0800      00135 M7_MN1  MOVFW  INDF           ; Data byte to SSPBUF wait until gone
00136      SPIT           ; Not concerned with rx data
0000      M      LOCAL  SPIT0
M

```

```

0056 0093      M      MOVWF  SSPBUF
              M      BANK1
0057 1683      M      BSF  STATUS,RP0
0058 1C14      M  SPIT0  BTFSS  SSPSTAT,BF
0059 2858      M      GOTO  SPIT0
              M      BANK0
005A 1283      M      BCF  STATUS,RP0
005B 0813      M      MOVWF  SSPBUF
              M
00137
005C 0A84      00138      INCF  FSR
005D 0BFC      00139      DECFSZ ICNT
005E 2855      00140      GOTO  M7_MN1
00141
00142 ;=====;
00143 ;
00144 ; Clear the timeout counter so program can measure time between interrupts ;
00145 ; Wait until the transfer has ended as signaled by chip select going high ;
00146 ; Restore the saved values of W,STATUS,FSR and return ;
00147 ;-----;

00148 ;
005F 1C06      00149 M7_NXT  BTFSS  ZCSIN      ; Wait till end of transfer
0060 285F      00150      GOTO  M7_NXT
00151
0061 1F14      00152      BTFSS  SSPCON,SSPOV    ; Test for data overrun
0062 2867      00153      GOTO  M7_NOR      ; no overrun
00154
00155      MOVLF  I_SSPCON,SSPCON    ; Reset the SP system
0063 3004      M      MOVLW  0X04
0064 0094      M      MOVWF  SSPCON
00156      MOVWF  SSPBUF      ; Clear the overrun data
0065 0813      00157      BSF  SSPCON,SSPEN    ; Reenable the SPI
0066 1694      00158
00159 M7_NOR  CLRf  TCNT      ; Clear the timeout counter
0067 01FB      00160      BCF  INTCON,INTF    ; Clear the interrupt flag
0068 108B      00161
00162      MOVF  FSAVE,W      ; Restore context
0069 087F      00163      MOVWF  FSR
006A 0084      00164      SWAPF  SSAVE,W
006B 0E7E      00165      MOVWF  STATUS
006C 0083      00166      SWAPF  WSAVE,F
006D 0EFD      00167      SWAPF  WSAVE,W
006E 0E7D      00168
00169      RETFIE      ; and return
006F 0009      00170
00171
00172
00284
0100      00285      ORG  0X100
0100      00286  START
00287      INCLUDE INITIAL.INC

```

```

00001          PAGE
00002          SUBTITLE " Initial code up to contact"
00003
00004 ; This MODULE contains the code that runs after a restart until receiving
00005 ; a NULL request from the SPI
00006
00007 ;### SECTION 1-1 #####;
00008 ; ;
00009 ; Sets the Status words according to the reset mode ;
00010 ; _____;
00011
00012          BANK00 ;
0100 1283          M          BCF STATUS,RP0
0101 1303          M          BCF STATUS,RP1
00013
0102 01C0          00014          CLRFB          _COMMAND
0103 01A1          00015          CLRFB          _STATUS2 ; Clear the secondary status word
00016
00017          MOVLF 0XF1,_STATUS1 ; Set reset status in primary word to 1
0104 30F1          M          MOVLW 0XF1
0105 00A0          M          MOVWF 0X20
00018 ; PSU and EDFA and NOSN to ones
00019          BANK1
0106 1683          M          BSFB STATUS,RP0
0107 1C8E          00020          BTFSS PCON,PORN ; PCON is in bank 1, STATUS is mapped
0108 2912          00021          GOTO M11_POR
0109 1C0E          00022          BTFSS PCON,BORN
010A 2910          00023          GOTO M11_BOR
010B 1E03          00024          BTFSS STATUS,TON
010C 290E          00025          GOTO M11_WDT
010D 2914          00026          GOTO M11_MCR
00027
00028 M11_WDT BANK0
010E 1283          M          BCF STATUS,RP0
010F 0AA0          00029          INCF _STATUS1,F
00030 M11_BOR BANK0
0110 1283          M          BCF STATUS,RP0
0111 0AA0          00031          INCF _STATUS1,F
00032 M11_POR BANK0
0112 1283          M          BCF STATUS,RP0
0113 0AA0          00033          INCF _STATUS1,F
00034
00035 M11_MCR BANK1 ; PCON is in bank 1, STATUS is mapped
0114 1683          M          BSFB STATUS,RP0
0115 148E          00036          BSFB PCON,PORN
0116 140E          00037          BSFB PCON,BORN
0117 1603          00038          BSFB STATUS,TON
00039
00040 ;=== SECTION 1-2 =====;
00041 ; ;
00042 ; Sets the configuration registers and sets all output pins to their ;
00043 ; inactive values ;
00044 ; _____;

```

		00045	
		00046	BANK0
0118	1283	M	BCF STATUS,RP0
		00047	
		00048	MOVLW I_PORTB,PORTB
0119	30FF	M	MOVLW 0XFF
011A	0086	M	MOVWF PORTB
		00049	MOVLW I_PORTC,PORTC
011B	30C0	M	MOVLW 0XC0
011C	0087	M	MOVWF PORTC
		00050	MOVLW I_PORTD,PORTD
011D	30FC	M	MOVLW 0XFC
011E	0088	M	MOVWF PORTD
		00051	MOVLW I_PORTE,PORTE
011F	30F0	M	MOVLW 0XF0
0120	0089	M	MOVWF PORTE
		00052	
		00053	MOVLW I_INTCON,INTCON
0121	3010	M	MOVLW 0X10
0122	008B	M	MOVWF INTCON
		00054	MOVLW I_ADCON0,ADCON0
0123	3080	M	MOVLW 0X80
0124	009F	M	MOVWF ADCON0
		00055	MOVLW I_SSPCON,SSPCON
0125	3004	M	MOVLW 0X04
0126	0094	M	MOVWF SSPCON
		00056	MOVLW I_T1CON,T1CON
0127	3031	M	MOVLW 0X31
0128	0090	M	MOVWF T1CON
		00057	
		00058	BANK1
0129	1683	M	BSF STATUS,RP0
		00059	
		00060	MOVLW I_OPTION,OPTION_REG
012A	300F	M	MOVLW 0X0F
012B	0081	M	MOVWF OPTION_REG
		00061	MOVLW I_ADCON1,ADCON1
012C	3085	M	MOVLW 0X85
012D	009F	M	MOVWF ADCON1
		00062	MOVLW I_SSPSTAT,SSPSTAT
012E	3000	M	MOVLW 0X00
012F	0094	M	MOVWF SSPSTAT
		00063	
		00064	MOVLW I_TRISA,TRISA
0130	30FF	M	MOVLW 0XFF
0131	0085	M	MOVWF TRISA
		00065	MOVLW I_TRISB,TRISB
0132	3001	M	MOVLW 0X01
0133	0086	M	MOVWF TRISB
		00066	MOVLW I_TRISC,TRISC
0134	301A	M	MOVLW 0X1A
0135	0087	M	MOVWF TRISC
		00067	MOVLW I_TRISD,TRISD

```

0136 3000      M    MOVLW  0X00
0137 0088      M    MOVWF  TRISD
00068          MOVLF  I_TRISE,TRISE
0138 3004      M    MOVLW  0X04
0139 0089      M    MOVWF  TRISE
00069
013A 0000      00070      NOP
00071
00072 ;=== SECTION 1-4 =====;
00073 ;                               ;
00074 ; Clears actual and fault value locations TO INVALID ;
00075 ; _____;
00076
00077          MOVLF  30,SCNT
013B 301E      M    MOVLW  30
013C 00F1      M    MOVWF  0X71
00078          MOVLF  EXTERNAL_VALUES_BASE,FSR
013D 3022      M    MOVLW  0X22
013E 0084      M    MOVWF  FSR
00079
00080          MOVLW  0XFF
0140 0080      00081 M14_1 MOVWF  INDF
0141 0A84      00082          INCF  FSR,F
0142 0BF1      00083          DECFSZ SCNT
0143 2940      00084          GOTO  M14_1
00085
0144 14A8      00086          BSF   _VNVAL_M,1
00087
00088 ;=== SECTION 1-4 =====;
00089 ;                               ;
00090 ; Copies parameters and limits from the EEPROM into the M&C registers. ;
00091 ; _____;
00092
00093          CALL   EEPROM_READ
0145 26AB      00094          NOP
0146 0000
00095 ;
00096 ;=== SECTION 1-4 =====;
00097 ;                               ;
00098 ; Generates CRC of Code . ;
00099 ; _____;
00100
00101          MOVLW  PROGBLOCKS
0147 3008      00102          CALL  CRC
0148 25AE      00103          NOP
0149 0000      00104
00105 ;=== SECTION 1-3 =====;
00106 ;                               ;
00107 ; loads the version number anTld gets the serial number from the SN pin. ;
00108 ; Time out checks are made to ensure that a serial number is being read but ;
00109 ; do not check that activity is within spec. ;
00110 ; _____;
00111
014A 0000      00112          NOP

```

```

00113
00114      BANK0
014B  1283      M      BCF STATUS,RP0
00115      MOVLF   I_VN_M,_VN_M      ; Put version number in M&C reg
014C  3004      M      MOVLW  0X04
014D  00E6      M      MOVWF   0X66
00116      MOVLF   I_VN_L,_VN_L
014E  3001      M      MOVLW  0X01
014F  00E7      M      MOVWF   0X67
00117
00118
0150  01E4      00119      CLRF    _SN_M
0151  01E5      00120      CLRF    _SN_L
00121
00122      MOVLF   8,SCNT
0152  3008      M      MOVLW  8
0153  00F1      M      MOVWF   0X71
0154  1286      00123      BCF    SNREQN      ; Request the serial number by resetting the SN-PIC
0155  0BF1      00124 M13_RST DECFSZ SCNT,F      ; for 24 cycles (4.8uS)
0156  2955      00125      GOTO   M13_RST
0157  1686      00126      BSF    SNREQN
00127
00128      MOVLF   4,LCNT      ; Allow an extra 1mS for the SN-PIC to send the first low
0158  3004      M      MOVLW  4
0159  00F2      M      MOVWF   0X72
015A  01F1      00129 S13_FL0 CLRF    SCNT
015B  1D09      00130 S13_FL1 BTFSS  SNIN
015C  2961      00131      GOTO   S13_FL2
015D  0BF1      00132      DECFSZ SCNT,F
015E  295B      00133      GOTO   S13_FL1
015F  0BF2      00134      DECFSZ LCNT,F
0160  295A      00135      GOTO   S13_FL0
00136
00137 S13_FL2 MOVLF  0X10,LCNT
0161  3010      M      MOVLW  0X10
0162  00F2      M      MOVWF   0X72
00138
00139 S13_LOP MOVLF  100,SCNT
0163  3064      M      MOVLW  100
0164  00F1      M      MOVWF   0X71
0165  1D09      00140 S13_L1 BTFSS  SNIN      ; Wait for pin to go low on subsequent bits
0166  296A      00141      GOTO   S13_B0      ; Fail if not seen within 100 loops
0167  0BF1      00142      DECFSZ SCNT,F      ; of 5 cycles ~ 100uS
0168  2965      00143      GOTO   S13_L1
0169  297F      00144      GOTO   S13_NOS
00145
00146 S13_B0 MOVLF  50,SCNT      ; Wait 50*5 cycles = 50uS to get to
016A  3032      M      MOVLW  50
016B  00F1      M      MOVWF   0X71
016C  0000      00147 S13_B1 NOP
016D  0000      00148      NOP
016E  0BF1      00149      DECFSZ SCNT,F      ; centre of bit cell
016F  296C      00150      GOTO   S13_B1

```



```

00151
0170 1003 00152      BCF  STATUS,C      ; Copy the bit value into carry
0171 1909 00153      BTFSC SNIN
0172 1403 00154      BSF  STATUS,C
00155
0173 0DE5 00156      RLF  _SN_L,F      ; Double length left shift
0174 0DE4 00157      RLF  _SN_M,F      ; picking up carry
00158
00159
00160      MOVLF  50,SCNT
0175 3032      M      MOVLW  50
0176 00F1      M      MOVWF  0X71
00161 S13_H1 BTFSC  SNIN      ; Wait for pin to go high
0177 1909 00162      GOTO  S13_NXT      ; Fail if not seen within 100 loops
0178 297C 00163      DECFSZ SCNT,F      ; of 5 cycles = ~ 100uS
0179 0BF1 00164      GOTO  S13_H1
017A 2977 00165      GOTO  S13_NOS
017B 297F 00166
00167 S13_NXT DECFSZ  LCNT,F
017C 0BF2 00168      GOTO  S13_LOP
017D 2963 00169
00170      BCF  ST1_NOSN
017E 12A0 00171
00172 S13_NOS NOP
017F 0000 00173
00174
00175
00176
00177 ;=== SECTION 1-5 =====
00178 ;
00179 ; Initialise the SPI system and wait for a NULL transfer to be sent. ;
00180 ; _____ ;
00181
00182      BANK0
0180 1283      M      BCF  STATUS,RP0
0181 1694 00183      BSF  SSPCON,SSPEN      ; Enable SSI
00184
00185 S15_1  MOVLF  BLOCKLEN,LCNT      ; Null transfer is 2 more than
0182 3020      M      MOVLW  32
0183 00F2      M      MOVWF  0X72
00186      ADDLF  2,LCNT,F      ; longest block (10 bytes in final)
0184 3002      M      MOVLW  2
0185 07F2      M      ADDWF  0X72,F
00187
00188 S15_3  MOVLW  MC_ACK      ; Send anything
00189      SPIT      ; Wait for received data
00189      LOCAL  SPIT0
00189      M
0187 0093      M      MOVWF  SSPBUF
00187      M
00188      BANK1
0188 1683      M      BSF  STATUS,RP0
0189 1C14      M  SPIT0 BTFSS  SSPSTAT,BF
018A 2989      M      GOTO  SPIT0

```

```

M      BANK0
018B  1283      M      BCF STATUS,RP0
018C  0813      M      MOVFW  SSPBUF
M
018D  3800      00190      IORLW  0          ; To test W
018E  1D03      00191      SKPZ
018F  2982      00192      GOTO   S15_1          ; If not zero then start again
0190  0BF2      00193      DECFSZ LCNT
0191  2986      00194      GOTO   S15_3
00195
0192  01FB      00196      CLRFB TCNT          ; Clear the time out counter
0193  1C06      00197 S15_2      BTFSS  ZCSIN
0194  2993      00198      GOTO   S15_2          ; Wait until CS/ clears
0195  0000      00199      NOP
0196  0000      00200      NOP
0197  108B      00201      BCF    INTCON,INTF    ; clear the external interrupt flag
0198  0000      00202      NOP
0199  0000      00203      NOP
019A  178B      00204      BSF    INTCON,GIE     ; then enable interrupts
00205
00206
00207
00288      INCLUDE  STARTUP.INC

00001      PAGE
00002      SUBTITLE " Startup PSUs and EDFA"
00003 ;
00004 ; This MODULE performs initial measurements before running the main loop
00005 ; First set up the DAC converters in the Receiver control loop.
00006 ; Then check the control voltage and temperature and if is safe to turn on
00007 ; the powers supplies and enable the EDFA dos so
00008 ;
00009 ;#####;
00010 ; ;
00011 ; This macro sends the tweak values to the three external DAC channels ;
00012 ; _____;
00013
00014 TWEAK  MACRO
00015      LOCAL  TWK0
00016
00017      CLRFB LCNT          ;
00018
00019 TWK0   MOVFW  LCNT          ; W contains channel number
00020      CALL   XDAC
00021
00022      INCF   LCNT,F          ; 3 units plus initiate command
00023      SKPGEL LCNT,4
00024      GOTO   TWK0
00025
00026      ENDM
00027
00028 ;=== SECTION 2-1 =====;
00029 ; ;

```

```

00030 ; Send the tweak values to the three external DAC channels ;
00031 ; _____ ;
00032
00033          TWEAK
0000          M          LOCAL   TWK0
              M
019B 01F2    M          CLRFB   LCNT          ;
              M
019C 0872    M TWK0    MOVFB   LCNT          ; W contains channel number
019D 25D8    M          CALL    XDAC
              M
019E 0AF2    M          INCF    LCNT,F        ; 3 units plus initiate command
              M          SKPGBL LCNT,4
019F 3004    M          MOVLW   4           ; w := k
01A0 0272    M          SUBWF   0X72,W       ; w := reg1-k
01A1 1C03    M          SKPC          ; carry for +0 : reg1 >= k
01A2 299C    M          GOTO    TWK0
              M
01A3 0000    00034      NOP
              00035
              00036
00037 ;=== SECTION 2-2 =====;
00038 ; _____ ;
00039 ; Measure the control voltage and the temperature. ;
00040 ; If both are correct turn on the PSUs. ;
00041 ; It is safe to release the EDFA if only the control voltage is correct ;
00042 ; _____ ;
00043
01A4 3002    00044      MOVLW   PSU_VC        ; Measure the control voltage
01A5 263D    00045      CALL    IADC
01A6 1903    00046      SKPNZ
01A7 29AF    00047      GOTO    M22_VF        ; If out of limit goto volt fault
              00048
01A8 26E9    00049      CALL    EDFA_ON       ; Release the shutdown line
              00050      ; Turn off the LED Clear the status bit
              00051
01A9 3003    00052      MOVLW   PSU_TMP       ; Measure the temperature
01AA 263D    00053      CALL    IADC
01AB 1903    00054      SKPNZ
01AC 29B9    00055      GOTO    M22_TF        ; If out of limit goto temp fault
              00056
              00057
01AD 26EF    00058      CALL    PSU_ON        ; Turn the PSUs on delay 100mS
01AE 29BF    00059      GOTO    M22_NXT       ; Turn off the LED ; Clear the status bits
              00060
00061 ;--- Control Voltage Fault -----
00062
00063 M22_VF MOVFF  _VCVAL_M,_VCFLT_M      ; Save failing value
01AF 082C    M          MOVF    0X2C,W
01B0 00BC    M          MOVWF   0X3C
00064          MOVFF  _VCVAL_L,_VCFLT_L
01B1 082D    M          MOVF    0X2D,W
01B2 00BD    M          MOVWF   0X3D

```

```

00065      IORLF  ST2P_VCX,_STATUS2,F      ; Update Secondary status
01B3  3042      M      MOVLW  0X42
01B4  04A1      M      IORWF  0X21,F
00066
00067      MOVLW  PSU_TMP      ; Measure the temperature
01B5  3003
00068      CALL   IADC
01B6  263D
00069      SKPZ      ; If out of limit skip to temp fault
01B7  1D03
00070      GOTO   M22_NXT
01B8  29BF
00071
00072 ;--- Temperature Fault -----
00073
00074 M22_TF MOVFF  _TMPVAL_M, _TMPFLT_M      ; Save failing values
01B9  082E      M      MOVF   0X2E,W
01BA  00BE      M      MOVWF  0X3E
00075      MOVFF  _TMPVAL_L, _TMPFLT_L      ;
01BB  082F      M      MOVF   0X2F,W
01BC  00BF      M      MOVWF  0X3F
00076      IORLF  ST2P_TMPX,_STATUS2,F      ; Update Secondary status
01BD  3001      M      MOVLW  0X01
01BE  04A1      M      IORWF  0X21,F
00077
00078 ;-----
01BF  0000      00079 M22_NXT NOP
00080
00081
00289
00290 PATCH  NOP
01C0  0000
00291      NOP
01C1  0000
00292 ;      GOTO  PATCH
00293
00294      INCLUDE LOOP.INC

00001      PAGE
00002      SUBTITLE      "Main Loop"
00003
00004 ; This MODULE is the main loop.  It monitors the voltages, temperature and
00005 ; optical levels.  And handles commands sent by the M&C bus
00006
00007 MAIN_LOOP
01C2  0000      00008      NOP
00009
00010 ;=== SECTION 3-1 =====;
00011 ; Measures Vpos,Vneg and Temp.  If one of them fails and the PSUs are on the ;
00012 ; PSU fault routine is called.  The loop count is some what contrived as ;
00013 ; (due to a tragic hardware error) it must take values 0,1,3.  This is done ;
00014 ; by doubling and adding 1 (from carry), finishing when the count is 7 ;
00015 ; -----;
00016
00017 M31_L0 CLRF   LCNT
01C3  01F2
00018
00019 M31_L1 MOVWF  LCNT      ; W must contain channel number
01C4  0872
00020      CALL   IADC      ; make measurement
01C5  263D
00021      SKPZ
01C6  1D03

```

```

01C7  29CA      00022      GOTO    M31_L2      ; if no fault goto next loop
                                00023
01C8  0872      00024      MOVFW   LCNT        ; W must contain channel number
01C9  2678      00025      CALL    PFLT        ; for call to shut down routine
                                00026
01CA  1403      00027 M31_L2 BSF     STATUS,C    ; 2*LCNT+1
01CB  0DF2      00028      RLF     LCNT
01CC  1D72      00029      BTFSS  LCNT,2
01CD  29C4      00030      GOTO    M31_L1
                                00031
                                00032 ;=== SECTION 3-2 =====;
                                00033 ; Measures Vcon.  If it fails and the PSUs are on the PSU fault routine is ;
                                00034 ; called.  If the EDFA is enabled the optical fault routine is called ;
                                00035 ; -----;
                                00036
01CE  3002      00037      MOVLW  PSU_VC      ; W must contain channel number
01CF  263D      00038      CALL   IADC        ; make measurement
01D0  1D03      00039      SKPZ
01D1  29D6      00040      GOTO    M32_NXT    ; If no fault skip to end of section
                                00041
01D2  3002      00042      MOVLW  PSU_VC      ; W must contain channel number
01D3  2678      00043      CALL   PFLT        ; for call to PSU fault routine
                                00044
01D4  3003      00045      MOVLW  EDF_VC      ; W contains special code
01D5  2692      00046      CALL   EFLT        ; for call to optical fault routine
                                00047
01D6  0000      00048 M32_NXT
01D6  0000      00049      NOP
                                00050
                                00051 ;=== SECTION 3-3 =====;
                                00052 ; Measures the three optical levels.  If one of them fails and the EDFA is ;
                                00053 ; enabled the optical fault routine is called ;
                                00054 ; -----;
                                00055
01D7  01F2      00056      CLRFB  LCNT
                                00057
01D8  0872      00058 M33_L1 MOVFW   LCNT        ; W must contain channel number
01D9  25F7      00059      CALL   XADC        ; make measurement
01DA  1D03      00060      SKPZ
01DB  29DE      00061      GOTO    M33_L2    ; If no fault go to next loop
                                00062
01DC  0872      00063      MOVFW   LCNT        ; W must contain channel number
01DD  2692      00064      CALL   EFLT        ; for all the shut down routine
                                00065
01DE  0AF2      00066 M33_L2 INCF    LCNT
                                00067 SKPGEL LCNT,3
                                M      MOVLW  3      ; w := k
01DF  3003      M      SUBWF  0X72,W    ; w := reg1-k
01E0  0272      M      SKPC      ; carry for +0 : reg1 >= k
01E1  1C03
01E2  29D8      00068      GOTO    M33_L1
                                00069
                                00070 ;=== SECTION 3-4 =====;
                                00071 ; Check how many loops have been executed since an SPI interrupt reset TCNT ;

```

```

00072 ; If TCNT reaches 256 call for an EDFA shutdown. As the loop time is set to ;
00073 ; about 10mS this is a timeout of about 2.5 seconds ;
00074 ; _____ ;
00075
00076 IFNDEF EMULATOR
00077     INCFSZ TCNT ; Increment loop counter
00078     GOTO M34_NXT
00079     MOVLW EDF_TO ; SPI timeout
00080     CALL EFLT ; shut down EDFA
00081 M34_NXT
00082 ENDIF
00083 ;=== SECTION 3-5 =====;
00084 ; Check whether a command has been received or is active and deal with it ;
00085 ; _____ ;
00086
01E3 2400 00087     CALL CMD
00088
00089 ;=== SECTION 3-6 =====;
00090 ; Delay until ~10mS has elapsed. With maximum prescale of eight the LS byte ;
00091 ; Timer 1 overflows in ~400uS so a count of 25 in the MS byte is right ;
00092 ; _____ ;
00093
00094 M36_1 SKPGEL TMR1H,25
01E4 3019 M     MOVLW 25 ; w := k
01E5 020F M     SUBWF TMR1H,W ; w := reg1-k
01E6 1C03 M     SKPC ; carry for +0 : reg1 >= k
01E7 29E4 00095     GOTO M36_1
01E8 018E 00096     CLRF TMR1L
01E9 018F 00097     CLRF TMR1H
01EA 29C2 00098     GOTO MAIN_LOOP
00099
00100 ;-----
00295
00296     ORG 0X400
00297     INCLUDE COMMANDS.INC

00001     PAGE
00002     SUBTITLE "Command Handler Subroutine"
00003
00004 ; This SUBROUTINE examines the command register and branches to the appropriate
00005 ; command, if any. Note that commands 2-7, the calibrate commands modify
00006 ; themselves to 10-15 after the first pass
00007 ;
00008 ; The command register is cleared on successful completion of a command or
00009 ; set to a number > $80 if it fails
00010
00011 ;#####;
00012 ; This macro clears the calibration variables CAL0,1,2 CCNT and sets the flag;
00013 ; in _CMHD ;
00014 ; _____ ;
00015
00016 CALINIT MACRO
00017

```

```

00018          CLRF    CCNT
00019          CLRF    CAL0
00020          CLRF    CAL1
00021          CLRF    CAL2
00022          BSF     _COMMAND,3
00023
00024          ENDM
00025
00026 ;=====;
00027 ; This rather complex macro is used in the calibration loop. The parameter ;
00028 ; is set to zero to indicate a 0mW cal or to 1 to indicate a 1mW cal ;
00029 ; ;
00030 ; It accumulates the current value of an optical level into the three global ;
00031 ; registers CAL2,CAL1,CAL0 and increments the calibration count CCNT. ;
00032 ; ;
00033 ; When,after 256 loops,CCNT returns to zero the calibration is complete ;
00034 ; the accumulated value is divided by 256 (by discarding CAL0 and rounding). ;
00035 ; If the MS part of the result is reasonable the new calibration is ;
00036 ; written to RES_L and RES_M (RES_M only for the 1mW CAL) and _COMMAND set ;
00037 ; to zero ;
00038 ; ;
00039 ; For the 1mW cal reasonable means >0 and <=$0F. For the 0mW cal it means ;
00040 ; =0. If a fail occurs on the zero test _COMMAND is set to &FF. On the ;
00041 ; $0F test it is set to $FE. In neither case is the existing calibration ;
00042 ; altered ;
00043 ;-----;

```

```

00044
00045 CALIBRATE      MACRO   VAL_M,VAL_L,LIMIT,RES_M,RES_L
00046                LOCAL  CAL_0,CAL_1,CAL_A,CAL_X,CAL_Y
00047
00048                MOVFW  VAL_L          ; Two + three byte addition
00049                ADDWF  CAL0,F          ; results being accumulated in CAL0,1,2
00050                MOVFW  CAL1           ;
00051
00052                BTFSC  STATUS,C
00053                INCFSZ VAL_M
00054                ADDWF  VAL_M,W
00055                MOVWF  CAL1
00056
00057                BTFSC  STATUS,C
00058                INCF   CAL2,F
00059
00060
00061                INCFSZ CCNT            ; accumulate for 256 counts then
00062                RETURN                ; wind up
00063
00064                BTFSS  CAL0,7          ; If top bit of CAL0 is set then round up
00065                GOTO   CAL_A           ;
00066                INCF  CAL1            ; by incrementing CAL1
00067                SKPNZ                ; If that overflows to zero
00068                INCF  CAL2            ; then increment CAL2
00069
00070                ; Now check reasonable
00071 CAL_A          MOVLW  LIMIT
00072                TSTW
00073                SKPZ                  ; Skip if zero cal
00074                GOTO   CAL_1
00075
00076 CAL_0          TSTF   CAL2            ; Zero cal test
00077                SKPZ
00078                GOTO   CAL_X           ; Fail high if CAL2 is not zero
00079                MOVFF  CAL1,RES_L      ; save one byte
00080                CLRF  _COMMAND         ; set _COMMAND to 0 and finish
00081                RETURN
00082
00083 CAL_1          TSTF   CAL2            ; 1mW cal test
00084                SKPNZ
00085                GOTO   CAL_Y           ; Fail low if CAL2 is zero
00086
00087                SKPLEL CAL2,0X0E       ; OK if CAL2 < 15
00088                GOTO   CAL_X           ; Fail high
00089
00090                MOVFF  CAL2,RES_M      ; otherwise save both bytes
00091                MOVFF  CAL1,RES_L
00092                CLRF  _COMMAND         ; set _COMMAND to 0 and finish
00093                RETURN
00094
00095 CAL_X          MOVLW  0XFE,_COMMAND   ; set _COMMAND to 254 for too high

```



```

00096          RETURN          ; and finish
00097
00098 CAL_Y  MOVLF  0XFD,_COMMAND ; set _COMMAND to 253 for too low
00099          RETURN          ; and finish
00100
00101          ENDM
00102
00103 ;#####;
00104 ; Examine the command word and branch accordingly. The clumsy coding shows ;
00105 ; my apprehension about using computed gotos ;
00106 ; _____;
00107
00108
0400 1BC0 00109 CMD  BTFSCL _COMMAND,7 ; If _COMMAND is negative a failed
0401 0008 00110          RETURN          ; command has not yet been acknowledged
00111
0402 0840 00112          MOVF  _COMMAND,W ; Has a new command been received
0403 1903 00113          SKPNZ
0404 0008 00114          RETURN          ; No command
00115
00116          DECW
0405 3EFF          M  ADDLW  0XFF
0406 1903 00117          SKPNZ
0407 2C4A 00118          GOTO  CMD_1 ; Re-tweak
00119          DECW
0408 3EFF          M  ADDLW  0XFF
0409 1903 00120          SKPNZ
040A 2C7C 00121          GOTO  CMD_2 ; Initiate calibrate Rx0 at zero input
00122          DECW
040B 3EFF          M  ADDLW  0XFF
040C 1903 00123          SKPNZ
040D 2CAF 00124          GOTO  CMD_3 ; Initiate calibrate Rx1 at zero input
00125          DECW
040E 3EFF          M  ADDLW  0XFF
040F 1903 00126          SKPNZ
0410 2CE2 00127          GOTO  CMD_4 ; Initiate calibrate Rx2 at zero input
00128          DECW
0411 3EFF          M  ADDLW  0XFF
0412 1903 00129          SKPNZ
0413 2D15 00130          GOTO  CMD_5 ; Initiate calibrate Rx0 at 1mW input
00131          DECW
0414 3EFF          M  ADDLW  0XFF
0415 1903 00132          SKPNZ
0416 2D48 00133          GOTO  CMD_6 ; Initiate calibrate Rx1 at 1mW input
00134          DECW
0417 3EFF          M  ADDLW  0XFF
0418 1903 00135          SKPNZ
0419 2D7B 00136          GOTO  CMD_7 ; Initiate calibrate Rx2 at 1mWo input
00137          DECW
041A 3EFF          M  ADDLW  0XFF
041B 1903 00138          SKPNZ
041C 2C54 00139          GOTO  CMD_8 ; Reload parameters form EEPROM
00140          DECW

```

```

041D 3EFF          M   ADDLW  0XFF
041E 1903          00141 SKPNZ
041F 2C5A          00142 GOTO   CMD_9      ; Save parameters in EEPROM
                                00143 DECW
0420 3EFF          M   ADDLW  0XFF
0421 1903          00144 SKPNZ
0422 2C81          00145 GOTO   CMD_10     ; Continue calibrate Rx0 at zero input
                                00146 DECW
0423 3EFF          M   ADDLW  0XFF
0424 1903          00147 SKPNZ
0425 2CB4          00148 GOTO   CMD_11     ; Continue calibrate Rx1 at zero input
                                00149 DECW
0426 3EFF          M   ADDLW  0XFF
0427 1903          00150 SKPNZ
0428 2CE7          00151 GOTO   CMD_12     ; Continue calibrate Rx2 at zero input
                                00152 DECW
0429 3EFF          M   ADDLW  0XFF
042A 1903          00153 SKPNZ
042B 2D1A          00154 GOTO   CMD_13     ; Continue calibrate Rx0 at 1mW input
                                00155 DECW
042C 3EFF          M   ADDLW  0XFF
042D 1903          00156 SKPNZ
042E 2D4D          00157 GOTO   CMD_14     ; Continue calibrate Rx1 at 1mW input
                                00158 DECW
042F 3EFF          M   ADDLW  0XFF
0430 1903          00159 SKPNZ
0431 2D80          00160 GOTO   CMD_15     ; Continue calibrate Rx2 at 1mW input
                                00161 DECW
0432 3EFF          M   ADDLW  0XFF
0433 1903          00162 SKPNZ
0434 2C60          00163 GOTO   CMD_16     ; Turn PSUs off
                                00164 DECW
0435 3EFF          M   ADDLW  0XFF
0436 1903          00165 SKPNZ
0437 2C64          00166 GOTO   CMD_17     ; Turn PSUs on
                                00167 DECW
0438 3EFF          M   ADDLW  0XFF
0439 1903          00168 SKPNZ
043A 2C67          00169 GOTO   CMD_18     ; Assert EDFA shutdown
                                00170 DECW
043B 3EFF          M   ADDLW  0XFF
043C 1903          00171 SKPNZ
043D 2C6B          00172 GOTO   CMD_19     ; Deassert EDFA shutdown
                                00173 DECW
043E 3EFF          M   ADDLW  0XFF
043F 1903          00174 SKPNZ
0440 2C6E          00175 GOTO   CMD_20     ; Blank the LEDS
                                00176 DECW
0441 3EFF          M   ADDLW  0XFF
0442 1903          00177 SKPNZ
0443 2C72          00178 GOTO   CMD_21     ; Enable the LEDS
                                00179 DECW
0444 3EFF          M   ADDLW  0XFF

```

```

0445 1903      00180      SKPNZ
0446 2C76      00181      GOTO    CMD_22      ; Generate CRC
00182
00183      MOVLF    0XFF,_COMMAND ; Illegal command
0447 30FF      M      MOVLW  0XFF
0448 00C0      M      MOVWF  0X40
0449 0008      00184      RETURN
00185
00186
00187 ;=====;
00188 ; Simple commands ;
00189 ;-----;
00190
00191 CMD_1  TWEAK      ; Retweak
0000      M      LOCAL  TWK0
044A 01F2      M      CLRFB  LCNT      ;
00192      M
044B 0872      M TWK0  MOVFB  LCNT      ; W contains channel number
044C 25D8      M      CALL   XDAC
00193      M
044D 0AF2      M      INCF   LCNT,F      ; 3 units plus initiate command
00194      M      SKPGBL LCNT,4
044E 3004      M      MOVLW  4      ; w := k
044F 0272      M      SUBWF  0X72,W      ; w := reg1-k
0450 1C03      M      SKPC      ; carry for +0 : reg1 >= k
0451 2C4B      M      GOTO   TWK0
00195      M
0452 01C0      00192      CLRF   _COMMAND
0453 0008      00193      RETURN
00194
00195 CMD_8  MOVLF    36,SCNT      ; number of byte to read
0454 3024      M      MOVLW  36
0455 00F1      M      MOVWF  0X71
00196      MOVLF    EEPROM_START ; first address to indirect register
0456 3042      00196      MOVLF    EEPROM_START
0457 26AB      00197      CALL   EEPROM_READ
0458 01C0      00198      CLRF   _COMMAND
0459 0008      00199      RETURN
00200
00201 CMD_9  MOVLF    36,SCNT      ; number of byte to read
045A 3024      M      MOVLW  36
045B 00F1      M      MOVWF  0X71
00202      MOVLF    EEPROM_START ; first address to indirect register
045C 3042      00202      MOVLF    EEPROM_START
045D 26C6      00203      CALL   EEPROM_WRITE
045E 01C0      00204      CLRF   _COMMAND
045F 0008      00205      RETURN
00206
00207 CMD_16 MOVLF    PSU_MC      ; Turn off power supplies
0460 3004      00207      MOVLF    PSU_MC
0461 2678      00208      CALL   PFLT
0462 01C0      00209      CLRF   _COMMAND
0463 0008      00210      RETURN
00211
0464 26EF      00212 CMD_17 CALL   PSU_ON      ; Turn on power supplies

```

```

0465 01C0      00213      CLRF      _COMMAND
0466 0008      00214      RETURN
00215
0467 3004      00216 CMD_18  MOVLW    EDF_MC      ; EDFA shut down
0468 2692      00217      CALL      EFLT
0469 01C0      00218      CLRF      _COMMAND
046A 0008      00219      RETURN
00220
046B 26E9      00221 CMD_19  CALL      EDFA_ON     ; EDFA start up
046C 01C0      00222      CLRF      _COMMAND
046D 0008      00223      RETURN
00224
046E 30FF      00225 CMD_20  MOVLW    0XFF        ; LEDS all off
046F 2710      00226      CALL      LEDSINH
0470 01C0      00227      CLRF      _COMMAND
0471 0008      00228      RETURN
00229
0472 3000      00230 CMD_21  MOVLW    0X00        ; LEDS all on
0473 2710      00231      CALL      LEDSINH
0474 01C0      00232      CLRF      _COMMAND
0475 0008      00233      RETURN
00234
00235
0476 25AE      00236 CMD_22  CALL      CRC         ; Generate CRC
0477 01C0      00237      CLRF      _COMMAND
0478 0008      00238      RETURN
00239
00240      MOVLW    0XFF,_COMMAND ; Illegal command
0479 30FF      M        MOVLW    0XFF
047A 00C0      M        MOVWF    0X40
047B 0008      00241      RETURN
00242
00243
00244
00245 ;=====;
00246 ; Calibration commands. On the first pass these modify their command code ;
00247 ; so that initialization occurs only once. The return occurs within the ;
00248 ; macro CALIBRATE ;
00249 ;-----;
00250
00251 CMD_2      CALINIT
M
047C 01FA      M        CLRF      CCNT
047D 01F7      M        CLRF      CAL0
047E 01F8      M        CLRF      CAL1
047F 01F9      M        CLRF      CAL2
0480 15C0      M        BSF      _COMMAND,3
M
00252 CMD_10    CALIBRATE      _OPOVAL_M,_OPOVAL_L,0,_OP0CAL0,_OP0CAL0
0000      M        LOCAL    CAL_0,CAL_1,CAL_A,CAL_X,CAL_Y
M
0481 0823      M        MOVFW    0X23      ; Two + three byte addition
0482 07F7      M        ADDWF    CAL0,F      ; results being accumulated in CAL0,1,2

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```

0483  0878      M      MOVFW  CAL1      ;
M
0484  1803      M      BTFSC  STATUS,C
0485  0FA2      M      INCFSZ 0X22
0486  0722      M      ADDWF  0X22,W
0487  00F8      M      MOVWF  CAL1
M
0488  1803      M      BTFSC  STATUS,C
0489  0AF9      M      INCF   CAL2,F
M
M
048A  0FFA      M      INCFSZ  CCNT      ; accumulate for 256 counts then
048B  0008      M      RETURN      ; wind up
M
048C  1FF7      M      BTFSS  CAL0,7    ; If top bit of CAL0 is set then round up
048D  2C91      M      GOTO   CAL_A    ;
048E  0AF8      M      INCF   CAL1    ; by incrementing CAL1
048F  1903      M      SKPNZ  ; If that overflows to zero
0490  0AF9      M      INCF   CAL2    ; then increment CAL2
M
M      ; Now check reasonable
0491  3000      M CAL_A  MOVLW  0
M      TSTW
0492  3800      M      IORLW  0      ;
0493  1D03      M      SKPZ   ; Skip if zero cal
0494  2C9C      M      GOTO   CAL_1
M
0495  08F9      M CAL_0  TSTF   CAL2    ; Zero cal test
0496  1D03      M      SKPZ   ;
0497  2CA9      M      GOTO   CAL_X    ; Fail high if CAL2 is not zero
M      MOVFF  CAL1,0X58 ; save one byte
0498  0878      M      MOVF   0X78,W
0499  00D8      M      MOVWF  0X58
049A  01C0      M      CLRF  _COMMAND ; set _COMMAND to 0 and finish
049B  0008      M      RETURN
M
049C  08F9      M CAL_1  TSTF   CAL2    ; 1mW cal test
049D  1903      M      SKPNZ  ;
049E  2CAC      M      GOTO   CAL_Y    ; Fail low if CAL2 is zero
M
M      SKPLEL  CAL2,0X0E ; OK if CAL2 < 15
049F  0879      M      MOVF   0X79,W    ; w := reg1
04A0  3C0E      M      SUBLW  0X0E    ; w := k-reg1
04A1  1C03      M      SKPC   ; carry for +0 : reg1 <= k.
04A2  2CA9      M      GOTO   CAL_X    ; Fail high
M
M      MOVFF  CAL2,0X58 ; otherwise save both bytes
04A3  0879      M      MOVF   0X79,W
04A4  00D8      M      MOVWF  0X58
M      MOVFF  CAL1,0X58
04A5  0878      M      MOVF   0X78,W
04A6  00D8      M      MOVWF  0X58
04A7  01C0      M      CLRF  _COMMAND ; set _COMMAND to 0 and finish

```

```

04A8 0008      M          RETURN
M
M CAL_X  MOVLW  0XFE, _COMMAND ; set _COMMAND to 254 for too high
04A9 30FE      M          MOVLW  0XFE
04AA 00C0      M          MOVWF  0X40
04AB 0008      M          RETURN ; and finish
M
M CAL_Y  MOVLW  0XFD, _COMMAND ; set _COMMAND to 253 for too low
04AC 30FD      M          MOVLW  0XFD
04AD 00C0      M          MOVWF  0X40
04AE 0008      M          RETURN ; and finish
M
00253
00254 CMD_3    CALINIT
M
04AF 01FA      M          CLRF   CCNT
04B0 01F7      M          CLRF   CAL0
04B1 01F8      M          CLRF   CAL1
04B2 01F9      M          CLRF   CAL2
04B3 15C0      M          BSF   _COMMAND, 3
M
00255 CMD_11  CALIBRATE _OP1VAL_M, _OP1VAL_L, 0, _OP1CAL0, _OP1CAL0
0000          M          LOCAL  CAL_0, CAL_1, CAL_A, CAL_X, CAL_Y
M
04B4 0825      M          MOVFW  0X25 ; Two + three byte addition
04B5 07F7      M          ADDWF  CAL0, F ; results being accumulated in CAL0,1,2
04B6 0878      M          MOVFW  CAL1 ;
M
04B7 1803      M          BTFSC  STATUS, C
04B8 0FA4      M          INCFSZ 0X24
04B9 0724      M          ADDWF  0X24, W
04BA 00F8      M          MOVWF  CAL1
M
04BB 1803      M          BTFSC  STATUS, C
04BC 0AF9      M          INCF   CAL2, F
M
M
04BD 0FFA      M          INCFSZ  CCNT ; accumulate for 256 counts then
04BE 0008      M          RETURN ; wind up
M
04BF 1FF7      M          BTFSS  CAL0, 7 ; If top bit of CAL0 is set then round up
04C0 2CC4      M          GOTO   CAL_A ;
04C1 0AF8      M          INCF   CAL1 ; by incrementing CAL1
04C2 1903      M          SKPNZ ; If that overflows to zero
04C3 0AF9      M          INCF   CAL2 ; then increment CAL2
M
M ; Now check reasonable
04C4 3000      M CAL_A  MOVLW  0
M          TSTW
04C5 3800      M          IORLW  0 ;
04C6 1D03      M          SKPZ ; Skip if zero cal
04C7 2CCF      M          GOTO   CAL_1
M

```

```

04C8 08F9      M CAL_0  TSTF   CAL2           ; Zero cal test
04C9 1D03      M          SKPZ                ;
04CA 2CDC      M          GOTO   CAL_X        ; Fail high if CAL2 is not zero
M          MOVFF  CAL1,0X5B      ; save one byte
04CB 0878      M          MOVF   0X78,W        ;
04CC 00DB      M          MOVWF  0X5B        ;
04CD 01C0      M          CLRF   _COMMAND      ; set _COMMAND to 0 and finish
04CE 0008      M          RETURN
M
04CF 08F9      M CAL_1  TSTF   CAL2           ; 1mW cal test
04D0 1903      M          SKPNZ               ;
04D1 2CDF      M          GOTO   CAL_Y        ; Fail low if CAL2 is zero
M
M          SKPLEL  CAL2,0X0E      ; OK if CAL2 < 15
04D2 0879      M          MOVF   0X79,W        ; w := reg1
04D3 3C0E      M          SUBLW  0X0E        ; w := k-reg1
04D4 1C03      M          SKPC                ; carry for +0 : reg1 <= k.
04D5 2CDC      M          GOTO   CAL_X        ; Fail high
M
M          MOVFF  CAL2,0X5B      ; otherwise save both bytes
04D6 0879      M          MOVF   0X79,W        ;
04D7 00DB      M          MOVWF  0X5B        ;
M          MOVFF  CAL1,0X5B      ;
04D8 0878      M          MOVF   0X78,W        ;
04D9 00DB      M          MOVWF  0X5B        ;
04DA 01C0      M          CLRF   _COMMAND      ; set _COMMAND to 0 and finish
04DB 0008      M          RETURN
M
M CAL_X  MOVLF  0XFE,_COMMAND    ; set _COMMAND to 254 for too high
04DC 30FE      M          MOVLW  0XFE        ;
04DD 00C0      M          MOVWF  0X40        ;
04DE 0008      M          RETURN            ; and finish
M
M CAL_Y  MOVLF  0XFD,_COMMAND    ; set _COMMAND to 253 for too low
04DF 30FD      M          MOVLW  0XFD        ;
04E0 00C0      M          MOVWF  0X40        ;
04E1 0008      M          RETURN            ; and finish
M
00256
00257 CMD_4  CALINIT
M
04E2 01FA      M          CLRF   CCNT        ;
04E3 01F7      M          CLRF   CAL0        ;
04E4 01F8      M          CLRF   CAL1        ;
04E5 01F9      M          CLRF   CAL2        ;
04E6 15C0      M          BSF    _COMMAND,3  ;
M
00258 CMD_12 CALIBRATE          _OP2VAL_M,_OP2VAL_L,0,_OP2CAL0,_OP2CAL0
0000      M          LOCAL  CAL_0,CAL_1,CAL_A,CAL_X,CAL_Y
M
04E7 0827      M          MOVFW  0X27        ; Two + three byte addition
04E8 07F7      M          ADDWF  CAL0,F      ; results being accumulated in CAL0,1,2
04E9 0878      M          MOVFW  CAL1        ;

```

```

M
04EA 1803 M      BTFSC  STATUS,C
04EB 0FA6 M      INCFSZ  0X26
04EC 0726 M      ADDWF   0X26,W
04ED 00F8 M      MOVWF   CAL1
M
04EE 1803 M      BTFSC  STATUS,C
04EF 0AF9 M      INCF   CAL2,F
M
M
04F0 0FFA M      INCFSZ  CCNT      ; accumulate for 256 counts then
04F1 0008 M      RETURN      ; wind up
M
04F2 1FF7 M      BTFSS  CAL0,7    ; If top bit of CAL0 is set then round up
04F3 2CF7 M      GOTO   CAL_A    ;
04F4 0AF8 M      INCF   CAL1      ; by incrementing CAL1
04F5 1903 M      SKPNZ  ; If that overflows to zero
04F6 0AF9 M      INCF   CAL2      ; then increment CAL2
M
M      ; Now check reasonable
04F7 3000 M CAL_A  MOVLW  0
M      TSTW
04F8 3800 M      IORLW  0      ;
04F9 1D03 M      SKPZ   ; Skip if zero cal
04FA 2D02 M      GOTO   CAL_1
M
04FB 08F9 M CAL_0  TSTF   CAL2    ; Zero cal test
04FC 1D03 M      SKPZ   ;
04FD 2D0F M      GOTO   CAL_X    ; Fail high if CAL2 is not zero
M      MOVFF  CAL1,0X5E  ; save one byte
04FE 0878 M      MOVF   0X78,W
04FF 00DE M      MOVWF  0X5E
0500 01C0 M      CLRF  _COMMAND  ; set _COMMAND to 0 and finish
0501 0008 M      RETURN
M
0502 08F9 M CAL_1  TSTF   CAL2    ; 1mW cal test
0503 1903 M      SKPNZ
0504 2D12 M      GOTO   CAL_Y    ; Fail low if CAL2 is zero
M
M      SKPLEL  CAL2,0X0E  ; OK if CAL2 < 15
0505 0879 M      MOVF   0X79,W    ; w := reg1
0506 3C0E M      SUBLW  0X0E    ; w := k-reg1
0507 1C03 M      SKPC   ; carry for +0 : reg1 <= k.
0508 2D0F M      GOTO   CAL_X    ; Fail high
M
M      MOVFF  CAL2,0X5E  ; otherwise save both bytes
0509 0879 M      MOVF   0X79,W
050A 00DE M      MOVWF  0X5E
M      MOVFF  CAL1,0X5E
050B 0878 M      MOVF   0X78,W
050C 00DE M      MOVWF  0X5E
050D 01C0 M      CLRF  _COMMAND  ; set _COMMAND to 0 and finish
050E 0008 M      RETURN

```



```

M
M CAL_X  MOVLW  0XFE,_COMMAND  ; set _COMMAND to 254 for too high
050F  30FE
M      MOVLW  0XFE
0510  00C0
M      MOVWF  0X40
0511  0008
M      RETURN                ; and finish
M
M CAL_Y  MOVLW  0XFD,_COMMAND  ; set _COMMAND to 253 for too low
0512  30FD
M      MOVLW  0XFD
0513  00C0
M      MOVWF  0X40
0514  0008
M      RETURN                ; and finish
M
00259
00260 CMD_5  CALINIT
M
0515  01FA
M      CLRF   CCNT
0516  01F7
M      CLRF   CAL0
0517  01F8
M      CLRF   CAL1
0518  01F9
M      CLRF   CAL2
0519  15C0
M      BSF   _COMMAND,3
M
00261 CMD_13 CALIBRATE  _OPOVAL_M,_OPOVAL_L,1,_OP0CAL1_M,_OP0CAL1_L
M      LOCAL  CAL_0,CAL_1,CAL_A,CAL_X,CAL_Y
M
051A  0823
M      MOVFW  0X23            ; Two + three byte addition
051B  07F7
M      ADDWF  CAL0,F          ; results being accumulated in CAL0,1,2
051C  0878
M      MOVFW  CAL1            ;
M
051D  1803
M      BTFSC  STATUS,C
051E  0FA2
M      INCFSZ 0X22
051F  0722
M      ADDWF  0X22,W
0520  00F8
M      MOVWF  CAL1
M
0521  1803
M      BTFSC  STATUS,C
0522  0AF9
M      INCF   CAL2,F
M
M
0523  0FFA
M      INCFSZ  CCNT          ; accumulate for 256 counts then
0524  0008
M      RETURN                ; wind up
M
0525  1FF7
M      BTFSS  CAL0,7        ; If top bit of CAL0 is set then round up
0526  2D2A
M      GOTO   CAL_A          ;
0527  0AF8
M      INCF   CAL1          ; by incrementing CAL1
0528  1903
M      SKPNZ  CAL1          ; If that overflows to zero
0529  0AF9
M      INCF   CAL2          ; then increment CAL2
M
M
M      ; Now check reasonable
052A  3001
M CAL_A  MOVLW  1
M      TSTW
052B  3800
M      IORLW  0            ;
052C  1D03
M      SKPZ   CAL_1        ; Skip if zero cal
052D  2D35
M      GOTO   CAL_1
M
052E  08F9
M CAL_0  TSTF   CAL2        ; Zero cal test

```

```

052F 1D03      M          SKPZ                ;
0530 2D42      M          GOTO    CAL_X        ; Fail high if CAL2 is not zero
M          MOVFF   CAL1,0X57    ; save one byte
0531 0878      M          MOVF    0X78,W
0532 00D7      M          MOVWF   0X57
0533 01C0      M          CLRF   _COMMAND    ; set _COMMAND to 0 and finish
0534 0008      M          RETURN
M
0535 08F9      M CAL_1  TSTF    CAL2        ; 1mW cal test
0536 1903      M          SKPNZ
0537 2D45      M          GOTO    CAL_Y        ; Fail low if CAL2 is zero
M
M          SKPLEL  CAL2,0X0E    ; OK if CAL2 < 15
0538 0879      M          MOVF    0X79,W      ; w := reg1
0539 3C0E      M          SUBLW   0X0E      ; w := k-reg1
053A 1C03      M          SKPC      ; carry for +0 : reg1 <= k.
053B 2D42      M          GOTO    CAL_X        ; Fail high
M
M          MOVFF   CAL2,0X56    ; otherwise save both bytes
053C 0879      M          MOVF    0X79,W
053D 00D6      M          MOVWF   0X56
M          MOVFF   CAL1,0X57
053E 0878      M          MOVF    0X78,W
053F 00D7      M          MOVWF   0X57
0540 01C0      M          CLRF   _COMMAND    ; set _COMMAND to 0 and finish
0541 0008      M          RETURN
M
M CAL_X  MOVLF   0XFE,_COMMAND  ; set _COMMAND to 254 for too high
0542 30FE      M          MOVLW   0XFE
0543 00C0      M          MOVWF   0X40
0544 0008      M          RETURN            ; and finish
M
M CAL_Y  MOVLF   0XFD,_COMMAND  ; set _COMMAND to 253 for too low
0545 30FD      M          MOVLW   0XFD
0546 00C0      M          MOVWF   0X40
0547 0008      M          RETURN            ; and finish
M
00262
00263 CMD_6  CALINIT
M
0548 01FA      M          CLRF   CCNT
0549 01F7      M          CLRF   CAL0
054A 01F8      M          CLRF   CAL1
054B 01F9      M          CLRF   CAL2
054C 15C0      M          BSF    _COMMAND,3
M
00264 CMD_14 CALIBRATE    _OP1VAL_M,_OP1VAL_L,1,_OP1CAL1_M,_OP1CAL1_L
0000      M          LOCAL  CAL_0,CAL_1,CAL_A,CAL_X,CAL_Y
M
054D 0825      M          MOVFW  0X25        ; Two + three byte addition
054E 07F7      M          ADDWF  CAL0,F      ; results being accumulated in CAL0,1,2
054F 0878      M          MOVFW  CAL1        ;
M

```

```

0550 1803      M      BTFSC  STATUS,C
0551 0FA4      M      INCFSZ  0X24
0552 0724      M      ADDWF   0X24,W
0553 00F8      M      MOVWF   CAL1
M
0554 1803      M      BTFSC  STATUS,C
0555 0AF9      M      INCF   CAL2,F
M
M
0556 0FFA      M      INCFSZ  CCNT          ; accumulate for 256 counts then
0557 0008      M      RETURN          ; wind up
M
0558 1FF7      M      BTFSS  CAL0,7      ; If top bit of CAL0 is set then round up
0559 2D5D      M      GOTO   CAL_A      ;
055A 0AF8      M      INCF   CAL1      ; by incrementing CAL1
055B 1903      M      SKPNZ          ; If that overflows to zero
055C 0AF9      M      INCF   CAL2      ; then increment CAL2
M
M
M      ; Now check reasonable
055D 3001      M CAL_A  MOVLW  1
M      TSTW
055E 3800      M      IORLW  0          ;
055F 1D03      M      SKPZ          ; Skip if zero cal
0560 2D68      M      GOTO   CAL_1
M
0561 08F9      M CAL_0  TSTF   CAL2      ; Zero cal test
0562 1D03      M      SKPZ          ;
0563 2D75      M      GOTO   CAL_X      ; Fail high if CAL2 is not zero
M      MOVFF   CAL1,0X5A    ; save one byte
0564 0878      M      MOVF   0X78,W
0565 00DA      M      MOVWF  0X5A
0566 01C0      M      CLRF   _COMMAND    ; set _COMMAND to 0 and finish
0567 0008      M      RETURN
M
0568 08F9      M CAL_1  TSTF   CAL2      ; lmW cal test
0569 1903      M      SKPNZ          ;
056A 2D78      M      GOTO   CAL_Y      ; Fail low if CAL2 is zero
M
M      SKPLEL  CAL2,0X0E    ; OK if CAL2 < 15
056B 0879      M      MOVF   0X79,W      ; w := reg1
056C 3C0E      M      SUBLW  0X0E      ; w := k-reg1
056D 1C03      M      SKPC          ; carry for +0 : reg1 <= k.
056E 2D75      M      GOTO   CAL_X      ; Fail high
M
M      MOVFF   CAL2,0X59    ; otherwise save both bytes
056F 0879      M      MOVF   0X79,W
0570 00D9      M      MOVWF  0X59
M      MOVFF   CAL1,0X5A
0571 0878      M      MOVF   0X78,W
0572 00DA      M      MOVWF  0X5A
0573 01C0      M      CLRF   _COMMAND    ; set _COMMAND to 0 and finish
0574 0008      M      RETURN
M

```

```

M CAL_X  MOVLW  0XFE,_COMMAND ; set _COMMAND to 254 for too high
0575  30FE  M          MOVLW  0XFE
0576  00C0  M          MOVWF  0X40
0577  0008  M          RETURN ; and finish
M
M CAL_Y  MOVLW  0XFD,_COMMAND ; set _COMMAND to 253 for too low
0578  30FD  M          MOVLW  0XFD
0579  00C0  M          MOVWF  0X40
057A  0008  M          RETURN ; and finish
M
00265
00266 CMD_7  CALINIT
M
057B  01FA  M          CLRF   CCNT
057C  01F7  M          CLRF   CAL0
057D  01F8  M          CLRF   CAL1
057E  01F9  M          CLRF   CAL2
057F  15C0  M          BSF   _COMMAND,3
M
00267 CMD_15 CALIBRATE  _OP2VAL_M,_OP2VAL_L,1,_OP2CAL1_M,_OP2CAL1_L
0000  M          LOCAL  CAL_0,CAL_1,CAL_A,CAL_X,CAL_Y
M
0580  0827  M          MOVFW  0X27 ; Two + three byte addition
0581  07F7  M          ADDWF  CAL0,F ; results being accumulated in CAL0,1,2
0582  0878  M          MOVFW  CAL1 ;
M
0583  1803  M          BTFSC  STATUS,C
0584  0FA6  M          INCFSZ 0X26
0585  0726  M          ADDWF  0X26,W
0586  00F8  M          MOVWF  CAL1
M
0587  1803  M          BTFSC  STATUS,C
0588  0AF9  M          INCF   CAL2,F
M
M
0589  0FFA  M          INCFSZ  CCNT ; accumulate for 256 counts then
058A  0008  M          RETURN ; wind up
M
058B  1FF7  M          BTFSS  CAL0,7 ; If top bit of CAL0 is set then round up
058C  2D90  M          GOTO   CAL_A ;
058D  0AF8  M          INCF   CAL1 ; by incrementing CAL1
058E  1903  M          SKPNZ ; If that overflows to zero
058F  0AF9  M          INCF   CAL2 ; then increment CAL2
M
M ; Now check reasonable
0590  3001  M CAL_A  MOVLW  1
M          TSTW
0591  3800  M          IORLW  0 ;
0592  1D03  M          SKPZ ; Skip if zero cal
0593  2D9B  M          GOTO   CAL_1
M
0594  08F9  M CAL_0  TSTF   CAL2 ; Zero cal test
0595  1D03  M          SKPZ ;

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```

0596 2DA8      M      GOTO    CAL_X      ; Fail high if CAL2 is not zero
M      MOVFF   CAL1,0X5D    ; save one byte
0597 0878      M      MOVF    0X78,W
0598 00DD      M      MOVWF   0X5D
0599 01C0      M      CLRF   _COMMAND    ; set _COMMAND to 0 and finish
059A 0008      M      RETURN
M
059B 08F9      M CAL_1  TSTF    CAL2      ; 1mW cal test
059C 1903      M      SKPNZ
059D 2DAB      M      GOTO    CAL_Y      ; Fail low if CAL2 is zero
M
M      SKPLEL  CAL2,0X0E    ; OK if CAL2 < 15
059E 0879      M      MOVF    0X79,W      ; w := reg1
059F 3C0E      M      SUBLW  0X0E      ; w := k-reg1
05A0 1C03      M      SKPC
M      ; carry for +0 : reg1 <= k.
05A1 2DA8      M      GOTO    CAL_X      ; Fail high
M
M      MOVFF   CAL2,0X5C    ; otherwise save both bytes
05A2 0879      M      MOVF    0X79,W
05A3 00DC      M      MOVWF   0X5C
M      MOVFF   CAL1,0X5D
05A4 0878      M      MOVF    0X78,W
05A5 00DD      M      MOVWF   0X5D
05A6 01C0      M      CLRF   _COMMAND    ; set _COMMAND to 0 and finish
05A7 0008      M      RETURN
M
M CAL_X  MOVLF   0XFE,_COMMAND ; set _COMMAND to 254 for too high
05A8 30FE      M      MOVLW  0XFE
05A9 00C0      M      MOVWF   0X40
05AA 0008      M      RETURN      ; and finish
M
M CAL_Y  MOVLF   0XFD,_COMMAND ; set _COMMAND to 253 for too low
05AB 30FD      M      MOVLW  0XFD
05AC 00C0      M      MOVWF   0X40
05AD 0008      M      RETURN      ; and finish

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00268
00269
00270
00298

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INCLUDE SUBS.INC

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```

00001      PAGE
00002      SUBTITLE      "Other Subroutines"
00003
00004 ;=====
00005 ; Subroutine to calculate the CRC of PROGBLOCKS blocks of code ;
00006 ; ;
00007 ; Uses the polynomial x^16 + x^12 + x^5 + 1 with starting value 0xFF ;
00008 ; Words are extended to 16 bits ;
00009 ; ;
00010 ; On Exit  SHFT_M  undefined ;
00011 ;          SHFT_L  undefined ;
00012 ;          SCNT   zero ;

```

```

00013 ;          LCNT    zero          ;
00014 ;          ICNT    zero          ;
00015 ;          FSR     undefined     ;
00016 ; _____ ;
00017
00018          #DEFINE HASH_M  0X10
00019          #DEFINE HASH_L  0X12
00020
00021 CRC     BANK02
05AE  1283      M      BCF  STATUS,RP0
05AF  1703      M      BSF  STATUS,RP1
00022
00023          CLR  EEDRH          ; Upper byte of address
05B0  018F
00024          MOVLF PROGBLOCKS,SCNT ; Number of blocks
05B1  3008      M      MOVLW 8
05B2  00F1      M      MOVWF 0X71
00025
00026          MOVLW 0XFF          ; initialize the accumulator
05B3  30FF
00027          MOVWF SHFT_M
05B4  00F3
00028          MOVWF SHFT_L
05B5  00F4
00029
00030 CRC1     CLR  EEDR          ; Lower byte of address
05B6  018D
00031 CRC1     CLR  LCNT          ; Counts words in block
05B7  01F2
00032
00033 CRC2     BSF  STATUS,RP0      ; Bank 2->3
05B8  1683
00034 CRC2     BSF  EECON1,EEPGD   ; select program memory
05B9  178C
00035 CRC2     BSF  EECON1,RD      ; fire a read
05BA  140C
00036         NOP
05BB  0000
00037         NOP
05BC  0000
00038         BCF  STATUS,RP0      ; Bank 3->2
05BD  1283
00039
00040         MOVLF 16,ICNT          ; bit counter
05BE  3010      M      MOVLW 16
05BF  00FC      M      MOVWF 0X7C
00041 CRC3     RRF  EEDATA          ; 4 byte shift
05C0  0C8C
00042 CRC3     RRF  EEDATH          ; of data into
05C1  0C8E
00043 CRC3     RRF  SHFT_L          ; into accumulator
05C2  0CF4
00044 CRC3     RRF  SHFT_M
05C3  0CF3
00045
00046         BTFSS STATUS,C          ; if a carry out
05C4  1C03
00047         GOTO CRC4            ; then hash the acc
05C5  2DCA
00048         XORLF HASH_M,SHFT_M,F
05C6  3010      M      MOVLW 0X10
05C7  06F3      M      XORWF 0X73,F
00049         XORLF HASH_L,SHFT_L,F
05C8  3012      M      MOVLW 0X12
05C9  06F4      M      XORWF 0X74,F
00050
00051 CRC4     DECFSZ ICNT
05CA  0BFC
00052 CRC4     GOTO  CRC3
05CB  2DC0
00053
00054         INC  EEDR
05CC  0A8D
00055         DECFSZ LCNT
05CD  0BF2

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05CE  2DB8      00056      GOTO    CRC2
05CF  0A8F      00057
05CF  0A8F      00058      INCF    EEADRH
05D0  0BF1      00059      DECFSZ  SCNT
00060
00061      BANK00
05D1  1283      M      BCF    STATUS,RP0
05D2  1303      M      BCF    STATUS,RP1
00062      MOVFF  SHFT_M,_CRC_M
05D3  0873      M      MOVF   0X73,W
05D4  00E8      M      MOVWF  0X68
00063      MOVFF  SHFT_L,_CRC_L
05D5  0874      M      MOVF   0X74,W
05D6  00E9      M      MOVWF  0X69
00064
05D7  0008      00065      RETURN
00066
00067
00068 ;=====
00069 ; Subroutine to send 12 bit fine tune data to the external DAC ;
00070 ; ;
00071 ; On Entry  W contains the DAC number (0-2 or 3 for the initiate command) ;
00072 ; ;
00073 ; On Exit  SHFT_M  undefined ;
00074 ;          SHFT_L  undefined ;
00075 ;          SCNT    zero ;
00076 ;          FSR     undefined ;
00077 ;-----;
00078
05D8  3903      00079  XDAC   ANDLW  0X03
05D9  0084      00080      MOVWF  FSR ; Move W to FSR and multiply by two
05DA  1003      00081      BCF    STATUS,C ; so that it is the offset from base
05DB  0D84      00082      RLF    FSR,F ;
00083
05DC  2716      00084      CALL   XDLUT ; converts DAC number to control code in W
05DD  00F3      00085      MOVWF  SHFT_M ; and save
00086
05DE  3050      00087      MOVLW  FINE_TUNE_BASE ; Add offset to base
05DF  0784      00088      ADDWF  FSR,F ; to get address of MS Byte
00089
05E0  0800      00090      MOVF   INDF,W ; get MS byte to W
05E1  390F      00091      ANDLW  0X0F ; mask off permitted four bits
05E2  04F3      00092      IORWF  SHFT_M,F ; add the control code
00093
05E3  0A84      00094      INCF   FSR,F ; get the LS BYTE
05E4  0800      00095      MOVF   INDF,W
05E5  00F4      00096      MOVWF  SHFT_L
00097
00098      MOVLW  16,SCNT ; Loop counter
05E6  3010      M      MOVLW  16
05E7  00F1      M      MOVWF  0X71
05E8  1387      00099      BCF    DCSN ; enable chip select
00100

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05E9 0DF4      00101 XDAC_1 RLF      SHFT_L,F      ; Get top bit into carry
05EA 0DF3      00102      RLF      SHFT_M,F
00103
05EB 1803      00104      BTFSC     STATUS,C      ; and copy to output pin
05EC 1507      00105      BSF      DDO
05ED 1C03      00106      BTFSS     STATUS,C
05EE 1107      00107      BCF      DDO
00108
05EF 0000      00109      NOP
05F0 1407      00110      BSF      DCLK      ;Pulse the clock 400ns
05F1 0000      00111      NOP
05F2 1007      00112      BCF      DCLK
00113
05F3 0BF1      00114      DECFSZ   SCNT,F      ; Next Bit
05F4 2DE9      00115      GOTO     XDAC_1
05F5 1787      00116      BSF      DCSN      ; Disable chip select
00117
05F6 0008      00118      RETURN     ; and finish
00119
00120 ;=====;
00121 ; Subroutine to get twelve bit optical level data from the external ADC ;
00122 ; and check it against the limits. ;
00123 ; ;
00124 ; On entry W contains the ADC number (0-2) ;
00125 ; ;
00126 ; On exit SHFT_M undefined ;
00127 ; SHFT_L undefined ;
00128 ; SCNT zero ;
00129 ; FSR undefined ;
00130 ; STATUS,Z is clear if value was in limits, set otherwise ;
00131 ;-----;
00132
05F7 3903      00133 XADC      ANDLW    0X03
05F8 00F5      00134      MOVWF    TEMP0      ; Save W for limit check
00135
05F9 0084      00136      MOVWF    FSR      ; Move W to FSR and multiply by two
05FA 1003      00137      BCF      STATUS,C      ; so that it is the offset from base
05FB 0D84      00138      RLF      FSR,F      ;
00139
05FC 2720      00140      CALL     XALUT      ; Converts ADC number to command code in W
05FD 00F3      00141      MOVWF    SHFT_M      ; and move to register for sending
00142
05FE 3022      00143      MOVLW    EXTERNAL_VALUES_BASE ; Add offset to base
05FF 0784      00144      ADDWF    FSR,F      ; to get address of MS Byte
00145
00146      MOVLF    8,SCNT      ; Set up loop to send command byte
0600 3008      M      MOVLW    8
0601 00F1      M      MOVWF    0X71
0602 1307      00147      BCF      ACSN      ; Assert chip select
00148
0603 0DF3      00149 XADC_1 RLF      SHFT_M,F      ; Get top bit into carry
00150
0604 1803      00151      BTFSC     STATUS,C      ; and copy to output pin

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0605 1507      00152      BSF      DDO
0606 1C03      00153      BTFSS   STATUS,C
0607 1107      00154      BCF      DDO
00155
0608 0000      00156      NOP                      ; Pulse the clock
0609 1407      00157      BSF      DCLK
060A 0000      00158      NOP
060B 1007      00159      BCF      DCLK
00160
060C 0BF1      00161      DECFSZ  SCNT,F           ; Next Bit
060D 2E03      00162      GOTO    XADC_1
00163
00164      MOVLF   13,SCNT        ; prepare to acquire 12 bits in 13 clocks
060E 300D      M      MOVLW  13
060F 00F1      M      MOVWF  0X71
0610 01F3      00165      CLRFB   SHFT_M         ; first clock will acquire zero
0611 01F4      00166      CLRFB   SHFT_L         ; from pre cleared carry
0612 1003      00167      BCF     STATUS,C
00168
0613 0DF4      00169 XADC_2 RLF     SHFT_L,F       ; shift up, picking up new bit from carry
0614 0DF3      00170      RLF     SHFT_M,F       ; first time round will be zero
00171
0615 1407      00172      BSF     DCLK           ; Pulse the clock to get next bit
0616 0000      00173      NOP
0617 1007      00174      BCF     DCLK
0618 0000      00175      NOP
00176
0619 1887      00177      BTFSC   DDI           ; get the bit from the input pin
061A 1403      00178      BSF     STATUS,C      ; into carry.
061B 1C87      00179      BTFSS   DDI           ; last time round no data acquired
061C 1003      00180      BCF     STATUS,C
00181
061D 0BF1      00182      DECFSZ  SCNT,F       ; Next Bit
061E 2E13      00183      GOTO    XADC_2
061F 1707      00184      BSF     ACSN          ; Disable chip select
00185
00186      ; FSR still points to MS byte
00187      BSF     INDF,7       ; Set changing flag in MS byte
0620 1780      00188      INCF    FSR,F        ; Move to LS byte
0621 0A84      00189      MOVFF   SHFT_L,INDF  ; and store the value
00190
0622 0874      M      MOVF    0X74,W
0623 0080      M      MOVWF  INDF
0624 0384      00190      DECF    FSR,F        ; Back to MS byte
00191      MOVFF   SHFT_M,INDF ; and store the value (which clears the flag)
0625 0873      M      MOVF    0X73,W
0626 0080      M      MOVWF  INDF
00192
00193
00194 ;-----
00195 ; At this point the result is in SHFT_M (ms 4 bits) and SHFT_L (lower 8 bits)
00196 ; The upper limit test is made only on the ms 4 bits
00197 ; The lower limit test is made on the ls 8 bits if the ms 4 bits are zero
00198

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00199      MOVFF  TEMP0,FSR          ; Recover the channel number
0627  0875      M      MOVF      0X75,W
0628  0084      M      MOVWF   FSR
0629  1003      00200    BCF      STATUS,C          ; to FSR and multiply by two
062A  0D84      00201    RLF      FSR,F          ; so that it is the offset from base
00202
062B  3042      00203    MOVLW   EXTERNAL_LIMITS_BASE ; Add offset to base of limits
062C  0784      00204    ADDWF  FSR,F          ; to get address of upper limit
00205
062D  0800      00206    MOVFW  INDF          ; Get the upper limit to W
00207    SKPLTW SHFT_M          ; If value < upper limit OK
062E  0273      M      SUBWF  0X73,W          ; w := reg1-w
062F  1803      M      SKPNC          ; carry/ for - : reg1 < w
0630  2E3B      00208    GOTO   XADC_4          ; If value >= upper limit goto fault
00209
0631  08F3      00210    TSTF  SHFT_M          ; If ms value> 0 OK-above lower limit
0632  1D03      00211    SKPZ          ; ms value is zero - more tests needed
0633  2E39      00212    GOTO  XADC_3          ; > zero so finish OK
00213
0634  0A84      00214    INCF  FSR,F          ; FSR points to lower limit
0635  0800      00215    MOVFW  INDF          ; get lower limit to W
00216    SKPGEW SHFT_L          ; If value >= lower limit OK
0636  0274      M      SUBWF  0X74,W          ; w := reg1-w
0637  1C03      M      SKPC          ; carry for +0 : reg1 >= w
0638  2E3B      00217    GOTO  XADC_4          ; If value < lower limit then fault
00218
0639  1103      00219 XADC_3 BCF      STATUS,Z          ; No fault
063A  0008      00220    RETURN          ; Return with Z clear
00221
063B  1503      00222 XADC_4 BSF      STATUS,Z          ; Fault
063C  0008      00223    RETURN          ; Return with Z set
00224
00225 ;=====;
00226 ; Subroutine to get ten bit voltage or temperature data from the Internal ADC ;
00227 ; and check against limits ;
00228 ; ;
00229 ; On entry  W contains the channel select code(0-3) ;
00230 ; ;
00231 ; On exit   SCNT   zero ;
00232 ;          FSR   undefined ;
00233 ;          STATUS,Z is clear if value was in limits, set otherwise ;
00234 ;-----;
00235
00236
00237 ;*** The initial code has a wretched patch to swap bits 0 and 1 of W to
00238 ;*** compensate for a wiring error on the inputs to the analog mux
00239 ;*** which should be corrected on the next build of the board
00240 ;*** When patch is removed ember to retain MOVWF TEMP0
00241
00242
00243 IADC  BANK0
063D  1283      M      BCF  STATUS,RP0
00244

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063E 00F5      00245      MOVWF  TEMP0      ; Save W for limit check
00246
00247 ;*      BCF    PORTE,0      ; Patch removed
00248 ;*      BCF    PORTE,1      ;
00249 ;*      BTFSC  TEMP0,0      ;
00250 ;*      BSF    PORTE,1      ;
00251 ;*      BTFSC  TEMP0,1      ;
00252 ;*      BSF    PORTE,0      ;
00253
063F 1009      00254      BCF    PORTE,0      ;
0640 1875      00255      BTFSC  TEMP0,0      ;
0641 1409      00256      BSF    PORTE,0      ;
0642 1089      00257      BCF    PORTE,1      ;
0643 18F5      00258      BTFSC  TEMP0,1      ;
0644 1489      00259      BSF    PORTE,1      ;
00260
0645 0084      00261      MOVWF  FSR        ; Move W to FSR and multiply by two
0646 1003      00262      BCF    STATUS,C    ; so that it is the offset from base
0647 0D84      00263      RLF    FSR,F        ;
00264
0648 3028      00265      MOVLW  INTERNAL_VALUES_BASE ; Add offset to base of read values
0649 0784      00266      ADDWF  FSR,F        ; to get address of MS Byte
00267
064A 141F      00268      BSF    ADCON0,ADON ; turn on ADC
00269
00270      MOVLW  0X22,SCNT   ; wait Tacq = 20uS
064B 3022      M      MOVLW  0X22
064C 00F1      M      MOVWF  0X71
064D 0BF1      00271 IADC_1  DECFSZ  SCNT,F
064E 2E4D      00272      GOTO   IADC_1
00273
064F 151F      00274      BSF    ADCON0,GO    ; Start conversion
0650 191F      00275 IADC_2  BTFSC  ADCON0,GO    ; wait till finished
0651 2E50      00276      GOTO   IADC_2
00277
0652 101F      00278      BCF    ADCON0,ADON ; Turn off again
00279
0653 1780      00280      BSF    INDF,7       ; FSR is pointing to MS byte
00281      ; Set flag bit
00282      BANK1
0654 1683      M      BSF    STATUS,RP0
0655 0A84      00283      INCF   FSR,F        ; Advance FSR to LS byte
00284      MOVFF  ADRESL,INDF ; and store the value
0656 081E      M      MOVF   ADRESL,W
0657 0080      M      MOVWF  INDF
0658 00F4      00285      MOVWF  SHFT_L
00286
00287      BANK0
0659 1283      M      BCF    STATUS,RP0
065A 0384      00288      DECF   FSR,F        ; Back to the MS byte
00289      MOVFF  ADRESH,INDF ; store the value (which clears flag)
065B 081E      M      MOVF   ADRESH,W
065C 0080      M      MOVWF  INDF

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065D 00F3      00290      MOVWF  SHFT_M
                00291
065E 08F5      00292      TSTF   TEMP0
065F 1903      00293      BTFSC  STATUS,Z
0660 0000      00294      NOP                                ; PATCH TO FIND W=0
                00295
                00296 ;-----
00297 ; At this point the result is in SHFT_M (ms 2 bits) and SHFT_L (ls 8 bits)
00298 ; The test is only made on the ms 8 bits
00299
0661 0CF3      00300      RRF    SHFT_M,F                    ; Shift right two places
0662 0CF4      00301      RRF    SHFT_L,F                    ; so ms 8 bits are in SHFT_L
0663 0CF3      00302      RRF    SHFT_M,F
0664 0CF4      00303      RRF    SHFT_L,F
                00304
                00305      MOVFF  TEMP0,FSR                  ; Recover the channel number
0665 0875      M        MOVF  0X75,W
0666 0084      M        MOVWF FSR
0667 1003      00306      BCF    STATUS,C                    ; to FSR and multiply by two
0668 0D84      00307      RLF    FSR,F                       ; so that it is the offset from base
                00308
0669 3048      00309      MOVLW  INTERNAL_LIMITS_BASE       ; Add offset to base of limits
066A 0784      00310      ADDWF  FSR,F                       ; to get address of upper limit
                00311
066B 0800      00312      MOVFW  INDF                        ; Get the upper limit to W
                00313      SKPLTW SHFT_L                      ; If value < upper limit then no fault
066C 0274      M        SUBWF  0X74,W                ; w := reg1-w
066D 1803      M        SKPNC                        ; carry/ for - : reg1 < w
066E 2E76      00314      GOTO   IADC_4                      ; If value >= upper limit goto fault
                00315
066F 0A84      00316      INCF   FSR,F                       ; FSR points to lower limit
0670 0800      00317      MOVFW  INDF                        ; get lower limit to W
                00318      SKPGEW SHFT_L                      ; If value >= lower limit OK
0671 0274      M        SUBWF  0X74,W                ; w := reg1-w
0672 1C03      M        SKPC                        ; carry for +0 : reg1 >= w
0673 2E76      00319      GOTO   IADC_4                      ; If value < lower limit then fault
                00320
0674 1103      00321      BCF    STATUS, Z                    ; No fault
0675 0008      00322      RETURN                             ; Return with Z clear
                00323
0676 1503      00324 IADC_4 BSF    STATUS,Z                    ; Fault
0677 0008      00325      RETURN                             ; Return with Z set
                00326
00327 ;=====
00328 ; Subroutine called on a voltage or temperature fault after start up or for ;
00329 ; an M&C commanded PSU shutdown. IF the PSUs are not already shut down ;
00330 ; saves the values, shut down the PSUs and flag the status word ;
00331 ; ;
00332 ; An alternate entry point IFLT_X skips the PSU on check ;
00333 ; ;
00334 ; On entry W contains the reason for the call ;
00335 ; 0 - Vneg fault translates to status code $04 ;
00336 ; 1 - Vpos fault translates to status code $05 ;

```

```

00337 ;      2 - Vcon fault          translates to status code $06      ;
00338 ;      3 - Temp fault         translates to status code $07      ;
00339 ;      4 - M&C command        translates to status code $08      ;
00340 ;                                                                    ;
00341 ; On exit W contains 0X00 if the routine was executed          ;
00342 ;                or 0xFF if an immediate exit was taken        ;
00343 ; _____ ;
00344
0678  1B20  00345 PFLT   BTFSC   ST1_PSU      ; If PSU already shut down
0679  34FF  00346 RETLW   0XFF      ; return at once
00347
067A  3E04  00348 PFLT_X  ADDLW   4          ; Convert channel number to fault code in W
067B  390F  00349        ANDLW   0X0F
067C  04A1  00350        IORWF   _STATUS2,F    ; Update the secondary status word
00351
067D  0828  00352        MOVFF   _VNVAL_M,_VNFLT_M    ; Copy the current readings
067E  00B8  M        MOVF    0X28,W
M        MOVWF   0X38
00353        MOVFF   _VNVAL_L,_VNFLT_L    ; to the fault locations
067F  0829  M        MOVF    0X29,W
0680  00B9  M        MOVWF   0X39
00354        MOVFF   _VPVAL_M,_VPFLT_M
0681  082A  M        MOVF    0X2A,W
0682  00BA  M        MOVWF   0X3A
00355        MOVFF   _VPVAL_L,_VPFLT_L
0683  082B  M        MOVF    0X2B,W
0684  00BB  M        MOVWF   0X3B
00356        MOVFF   _TMPVAL_M,_TMPFLT_M
0685  082E  M        MOVF    0X2E,W
0686  00BE  M        MOVWF   0X3E
00357        MOVFF   _TMPVAL_L,_TMPFLT_L
0687  082F  M        MOVF    0X2F,W
0688  00BF  M        MOVWF   0X3F
00358        MOVFF   _VCVAL_M,_VCFLT_M
0689  082C  M        MOVF    0X2C,W
068A  00BC  M        MOVWF   0X3C
00359        MOVFF   _VCVAL_L,_VCFLT_L
068B  082D  M        MOVF    0X2D,W
068C  00BD  M        MOVWF   0X3D
00360
068D  1486  00361        BSF     VPENN      ; Turn of the two PSUs
068E  1506  00362        BSF     VNENN
068F  1088  00363        BCF     PSULEDN    ; Turn on the fault LED
00364
0690  1720  00365        BSF     ST1_PSU    ; Update the primary status word
00366
0691  0008  00367        RETURN
00368

```

```

00369 ;=====;
00370 ; Subroutine called on an optical fault or for an M&C commanded EDFA shutdown;
00371 ; If EDFA not already shut down - save the values, issue an EDFA shutdown ;
00372 ; command and flag the status word. ;
00373 ; ;
00374 ; An alternate entry point XFLT_X skips the EDFA check ;
00375 ; ;
00376 ; On entry W contains the reason for the call ;
00377 ; 0 - Rx0 fault translates to status code $10 ;
00378 ; 1 - Rx1 fault translates to status code $20 ;
00379 ; 2 - Rx2 fault translates to status code $30 ;
00380 ; 3 - Vcon Fault translates to status code $40 ;
00381 ; 4 - M&C command translates to status code $50 ;
00382 ; 5 - SPI timeout translates to status code $60 ;
00383 ; ;
00384 ; On exit W contains 0x00 if the routine was executed ;
00385 ; or 0xFF if an immediate return was taken ;
00386 ;-----;
00387
00388
00389
0692 1BA0 00390 EFLT BTFSC ST1_EDFA ; If EDFA already shut down
0693 34FF 00391 RETLW 0XFF ; return at once
00392
0694 3E01 00393 XFLT_X ADDLW 1 ; Convert channel number to fault code in W
0695 00F5 00394 MOVWF TEMP0
0696 0DF5 00395 RLF TEMP0
0697 0DF5 00396 RLF TEMP0
0698 0DF5 00397 RLF TEMP0
0699 0D75 00398 RLF TEMP0,W
00399
069A 04A1 00400 IORWF _STATUS2,F ; Update the secondary status word
00401
00402 MOVFF _OP0VAL_M,_OP0FLT_M ; Copy the current readings
069B 0822 M MOVF 0X22,W
069C 00B2 M MOVWF 0X32
00403 MOVFF _OP0VAL_L,_OP0FLT_L ; to the fault locations
069D 0823 M MOVF 0X23,W
069E 00B3 M MOVWF 0X33
00404 MOVFF _OP1VAL_M,_OP1FLT_M
069F 0824 M MOVF 0X24,W
06A0 00B4 M MOVWF 0X34
00405 MOVFF _OP1VAL_L,_OP1FLT_L
06A1 0825 M MOVF 0X25,W
06A2 00B5 M MOVWF 0X35
00406 MOVFF _OP2VAL_M,_OP2FLT_M
06A3 0826 M MOVF 0X26,W
06A4 00B6 M MOVWF 0X36
00407 MOVFF _OP2VAL_L,_OP2FLT_L
06A5 0827 M MOVF 0X27,W
06A6 00B7 M MOVWF 0X37
00408

```

```

06A7 1606      00409      BSF      EDFASD      ; Turn on the EDFA shut down line
06A8 1008      00410      BCF      EDFALEDN    ; Turn on the fault LED
                                00411
06A9 17A0      00412      BSF      ST1_EDFA    ; Update the primary status word
                                00413
06AA 0008      00414      RETURN
                                00415
                                00416 ;=====;
                                00417 ; This subroutine copies 33 parameters from EEPROM to RAM followed by the ;
                                00418 ; checksum ;
                                00419 ; ;
                                00420 ; On exit SCNT zero ;
                                00421 ; FSR undefined ;
                                00422 ; _____;
                                00423
                                00424      #DEFINE HASH      0X1D
06AB          00425      EEPROM_READ
                                00426
                                00427      MOVLW      34,SCNT
06AB 3022      M      MOVLW      34
06AC 00F1      M      MOVWF      0X71
                                00428      MOVLW      EEPROM_START,FSR; Start address to FSR
06AD 3042      M      MOVLW      0X42
06AE 0084      M      MOVWF      FSR
                                00429      BANK02
06AF 1283      M      BCF      STATUS,RP0
06B0 1703      M      BSF      STATUS,RP1
06B1 018D      00430      CLRF      EEADR
06B2 01F5      00431      CLRF      TEMP0      ; accumulator for checksum
                                00432
                                00433      EER_L1      BANK03      ; Bank 3
06B3 1683      M      BSF      STATUS,RP0
06B4 1703      M      BSF      STATUS,RP1
06B5 138C      00434      BCF      EECON1,EEPGD    ; point to EEPROM not PROG mem
06B6 140C      00435      BSF      EECON1,RD      ; fire a read
                                00436
                                00437      BCF      STATUS,RP0    ; Bank 3->2
06B7 1283      00438      MOVWF      EEDATA
06B8 080C      00439      MOVWF      INDF      ; Data to RAM at indirect pointer
06B9 0080      00440      XORWF      TEMP0      ; accumulate checksum
06BA 06F5      00441
                                00442 ;      MOVLW      HASH
                                00443 ;      RLF      EEDATA
                                00444 ;      RLF      TEMP0
                                00445 ;      BTFSC      STATUS,C
                                00446 ;      XORWF      TEMP0
                                00447
06BB 0A8D      00448      INCF      EEADR
06BC 0A84      00449      INCF      FSR,F      ; increment address
06BD 0BF1      00450      DECFSZ    SCNT,F
06BE 2EB3      00451      GOTO     EER_L1
                                00452
06BF 0875      00453      MOVWF      TEMP0      ; Also sets or clears Z |

```

```

06C0 1303      00454      BCF      STATUS,RP1      ; Bank 2->0
06C1 00E3      00455      MOVWF    _CHECKSUM      ;
                                00456      ;
06C2 1220      00457      BCF      ST1_EECSF      ;
06C3 1D03      00458      SKPZ     ; for use here  <--
06C4 1620      00459      BSF      ST1_EECSF
                                00460
06C5 0008      00461      RETURN
                                00462
                                00463 ;=====;
                                00464 ; This subroutine copies 33 parameters from RAM to EEPROM accumulating a ;
                                00465 ; checksum in _CHECKSUM and writing this to the 34th line of EEPROM ;
                                00466 ; ;
                                00467 ; On exit SCNT zero ;
                                00468 ; FSR undefined ;
                                00469 ; _CHECKSUM zero ;
                                00470 ;-----;
                                00471
06C6          00472 EEPROM_WRITE
                                00473
                                00474      MOVLF    34,SCNT
06C6 3022      M      MOVLW  34
06C7 00F1      M      MOVWF   0X71
06C8 01E3      00475      CLRF    _CHECKSUM
                                00476      MOVLF    EEPROM_START,FSR      ; Start address to FSR
06C9 3042      M      MOVLW  0X42
06CA 0084      M      MOVWF   FSR
                                00477      BANK02
06CB 1283      M      BCF     STATUS,RP0
06CC 1703      M      BSF     STATUS,RP1
06CD 018D      00478      CLRF    EEADR
                                00479
06CE 1703      00480 EEW_L1 BSF     STATUS,RP1      ; Bank 0->2
                                00481      MOVFF   INDF,EEDATA      ; Data from RAM at indirect pointer
06CF 0800      M      MOVF    INDF,W
06D0 008C      M      MOVWF   EEDATA
                                00482
                                00483      BSF     STATUS,RP0      ; Bank 2->3
06D1 1683      00484      BCF     EECON1,EEPGD      ; point to EEPROM not PROG mem
06D2 138C      00485      BSF     EECON1,WREN      ; enable writes
06D3 150C      00486
                                00487      BCF     INTCON,GIE      ; disable interrupts for safety
06D4 138B      00488      MOVLF   0X55,EECON2      ; write $55
06D5 3055      M      MOVLW  0X55
06D6 008D      M      MOVWF   EECON2
                                00489      MOVLF   0XAA,EECON2      ; then $AA to prime write
06D7 30AA      M      MOVLW  0XAA
06D8 008D      M      MOVWF   EECON2
06D9 148C      00490      BSF     EECON1,WR      ; fire the write
06DA 178B      00491      BSF     INTCON,GIE      ; reenable interrupts
                                00492
06DB 188C      00493 EEW_WT BTFSC   EECON1,WR      ; wait till write complete
06DC 2EDB      00494      GOTO    EEW_WT

```



```

06DD 110C      00495      BCF      EECON1,WREN      ; then disable writes
                00496
06DE 1283      00497      BCF      STATUS,RP0      ; Bank 3->2
06DF 0A8D      00498      INCF     EEADR,F
06E0 080C      00499      MOVFW    EEDATA
                00500
06E1 1303      00501      BCF      STATUS,RP1      ; Bank 2->0
06E2 06E3      00502      XORWF    _CHECKSUM,F
                00503
06E3 0A84      00504      INCF     FSR,F           ; increment address
06E4 0BF1      00505      DECFSZ   SCNT,F
06E5 2ECE      00506      GOTO     EEW_L1
                00507
                00508      BANK00
06E6 1283      M          BCF      STATUS,RP0
06E7 1303      M          BCF      STATUS,RP1
06E8 0008      00509      RETURN
                00510
00511 ;          BCF      STATUS,RP0      ; Bank 3->2;
00512 ;
00513 ;          INCF     EEADR,F
00514 ;          MOVLW    HASH           ; Prepare for a possible hash
00515 ;          RLF      EEDATA         ; Shift the data into carry
00516 ;
00517 ;          BCF      STATUS,RP1      ; Bank 2->0
00518 ;          RLF      _CHECKSUM,F     ; Shift data on into acc
00519 ;          BTFSC   STATUS,C         ; if bit drops out
00520 ;          XORWF    _CHECKSUM,F     ; then hash
00521 ;
00522 ;          INCF     FSR,F           ; increment address
00523 ;          DECFSZ   SCNT,F
00524 ;          GOTO     EEW_L1
00525 ;
00526 ;          BANK00
00527 ;          RETURN
00528
00529 ;=====;
00530 ; This subroutine releases the EDFA ;
00531 ;=====;
00532
06E9 1206      00533 EDFA_ON BCF      EDFASD         ; Release the shutdown line
                00534
06EA 1408      00535      BSF      EDFALDN         ; Turn off the LED
06EB 13A0      00536      BCF      ST1_EDFA        ; Clear the status bit
00537      ANDLF    0X0F,_STATUS2,F
06EC 300F      M          MOVLW    0X0F
06ED 05A1      M          ANDWF    0X21,F
                00538
06EE 0008      00539      RETURN
                00540
00541 ;=====;
00542 ; This turns the PSUs on and waits ~100ms for them to stabilize ;
00543 ;=====;

```

```

00544
06EF 1106      00545 PSU_ON BCF    VNENN      ; Turn the PSUs on
06F0 1086      00546         BCF    VPENN      ;
00547
00548
00549 ;         CLRF   TMR1L;
00550 ;         MOVLW 0x01,TMR1H ; Set TIMER1 to 0x0100 (prescaler is 8)
00551 ;
00552 ;PSU_ON1   TSTF   TMR1H      ; Wait until it overflows to zero
00553 ;         SKPZ           ; This takes 255*256*8 clocks
00554 ;         GOTO   PSU_ON1    ; At 5MHz that is ~104mS
00555
00556         CLRF   LCNT
06F1 01F2      00557 PSU_ON1 CLRF   SCNT
06F2 01F1
06F3 0000      00558 PSU_ON2 NOP
06F4 0000      00559         NOP
06F5 0000      00560         NOP
06F6 0000      00561         NOP
06F7 0000      00562         NOP
06F8 0000      00563         NOP
06F9 0000      00564         NOP
06FA 0000      00565         NOP
06FB 0000      00566         NOP
06FC 0000      00567         NOP
06FD 0000      00568         NOP
06FE 0000      00569         NOP
06FF 0000      00570         NOP
0700 0000      00571         NOP
0701 0000      00572         NOP
0702 0000      00573         NOP
0703 0000      00574         NOP
0704 0000      00575         NOP
0705 0000      00576         NOP
0706 0000      00577         NOP
0707 0BF1      00578         DECFSZ SCNT
0708 2EF3      00579         GOTO   PSU_ON2
0709 0BF2      00580         DECFSZ LCNT
070A 2EF2      00581         GOTO   PSU_ON1
00582
070B 1488      00583         BSF    PSULEDN ; Turn off the LED
070C 1320      00584         BCF    ST1_PSU ; Clear the status bits
00585         ANDLF 0XF0,_STATUS2,F
070D 30F0      M     MOVLW 0XF0
070E 05A1      M     ANDWF 0X21,F
00586
070F 0008      00587         RETURN
00588

```

```

00589 ;=====;
00590 ; This subroutine inhibits select LEDS ;
00591 ; The W register contains a mask. A one inhibits the LED at that position ;
00592 ;-----;
00593
00594 LEDSIH BANK01
0710 1683 M BSF STATUS,RP0
0711 1303 M BCF STATUS,RP1
0712 0088 00595 MOVWF TRISD
00596 BANK00
0713 1283 M BCF STATUS,RP0
0714 1303 M BCF STATUS,RP1
0715 0008 00597 RETURN
00598
00599 ;#####*
00600 ; LOOK UP TABLES. These do not use computed GOTOs because of the
00601 ; difficulties with relocation and with interrupts
00602 ;
00603 ;
00604 ;== Look up table for control codes for external DAC =====
00605
00606 XDLUT TSTW
0716 3800 M IORLW 0 ;
0717 1903 00607 SKPNZ
0718 3410 00608 RETLW 0X10 ; W=0 control code to load input reg 0
00609 DECW
0719 3EFF M ADDLW 0XFF
071A 1903 00610 SKPNZ
071B 3450 00611 RETLW 0X50 ; W=1 control code to load input reg 1
00612 DECW
071C 3EFF M ADDLW 0XFF
071D 1903 00613 SKPNZ
071E 3490 00614 RETLW 0X90 ; W=2 control code to load input reg 2
071F 3440 00615 RETLW 0X40 ; W>2 control code to transfer input reg
00616
00617 ;== Look up table for control codes for external ADC =====
00618
00619 XALUT TSTW
0720 3800 M IORLW 0 ;
0721 1903 00620 SKPNZ
0722 3497 00621 RETLW 0X97 ; W=0 control code to read ADC 0
00622 DECW
0723 3EFF M ADDLW 0XFF
0724 1903 00623 SKPNZ
0725 34D7 00624 RETLW 0XD7 ; W=1 control code to read ADC 1
00625 DECW
0726 3EFF M ADDLW 0XFF
0727 1903 00626 SKPNZ
0728 34A7 00627 RETLW 0XA7 ; W=2 control code to read ADC 2
0729 34E7 00628 RETLW 0XE7 ; W=3 control code to read ADC 3
00629
00630

```

```

00631
00299
00300
00301 ;EEPROM
00302
2100 0000 0000 00303     ORG 0X2100
00304 ; Target 0x42
2100 0008 0008 00305     DE 0X08,0X08 ; uplimit/256 , low limit for Rx0
2102 0008 0008 00306     DE 0X08,0X08 ; uplimit/256 , low limit for Rx1
2104 0008 0008 00307     DE 0X08,0X08 ; uplimit/256 , low limit for Rx2
00308
00309 ;Target '0x48
00310 IFDEF TEST
00311     DE 0X99,0X66 ; Uplimit,lowlimit negative supply (2-3V)
00312     DE 0X99,0X66 ; Uplimit,lowlimit positive supply (2-3V)
00313     DE 0X99,0X66 ; Uplimit,lowlimit control supply (2-3V)
00314     DE 0XD0,0X00 ; Uplinit,lowlimit temperature (-60/70C)
00315 ELSE
2106 0028 0012 00316     DE 0X28,0X12 ; Uplimit,lowlimit negative supply (+_10%)
2108 00B4 0096 00317     DE 0XB4,0X96 ; Uplimit,lowlimit positive supply (+_10%)
210A 00E1 00AF 00318     DE 0XE1,0XAF ; Uplimit,lowlimit control supply (7-9V)
210C 0082 0000 00319     DE 0X82,0X00 ; Uplinit,lowlimit temperature (-60/70C)
00320 ENDIF
00321
00322 ; Target 0x50
210E 0002 0000 00323     DE 0X02,0X00 ; Fine tune Rx0 (Mid range)
2110 0002 0000 00324     DE 0X02,0X00 ; Fine tune Rx1 (Mid range)
2112 0002 0000 00325     DE 0X02,0X00 ; Fine tune Rx2 (Mid range)
00326
00327 ; Target 0x56
2114 0008 0000 0000 00328     DE 0X08,0X00,0X00 ; lmw, zero calcs Rx0
2117 0008 0000 0000 00329     DE 0X08,0X00,0X00 ; lmw, zero calcs Rx1
211A 0008 0000 0000 00330     DE 0X08,0X00,0X00 ; lmw, zero calcs Rx2
211D 0000 0000 0000 00331     DE 0X00 ; spare
00332
00333 ; Target 0x60
211E 0056 0066 0074 00334     DE 0X56,0X66,0X74 ; ID bytes for ID=666, fixed 8 byte length
00335 ; address space 256 mode 1
2121 009A 0000 0000 00336     DE 0X9A ; checksum
00337
00338
00339 ;=====
00340
00341     END

```

MEMORY USAGE MAP ('X' = Used, '-' = Unused)

```

0000 : X--XXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0040 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX -----
0100 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0140 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0180 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
01C0 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX-----
0400 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0440 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0480 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
04C0 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0500 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0540 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0580 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
05C0 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0600 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0640 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0680 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
06C0 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX
0700 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXX-----
2000 : XXXX--X----- -----
2100 : XXXXXXXXXXXXXXXXX XXXXXXXXXXXXXXXX XX-----

```

All other memory blocks unused.

Program Memory Words Used: 1154
Program Memory Words Free: 7038

```

Errors      :      0
Warnings    :      0 reported,      0 suppressed
Messages    :      0 reported,     95 suppressed

```